BR Series

CONTROLLERS

MOTION DEVICES

SOFTWARE

ribution

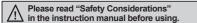
Cylindrical (Ø18mm) Type

Features

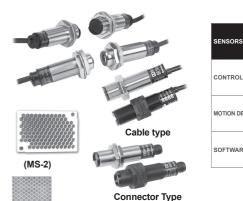
- Realizes long sensing distance (20m) (through-beam type)
- Superior noise resistance with digital signal processing
- High-speed response time under 1ms
- · Power reverse polarity protection circuit, output short over current protection circuit
- Suitable for sensing in narrow space (narrow beam type)
- External sensitivity adjustment (except through-beam type)
- Light ON, Dark ON switchable by control wire (except through-beam type)
- Excellent environment-resistance performance with glass lens(BR4M)

CE

Protection structure IP66 (IEC standard)



Specifications



%The model name with '-C' is connector type. XMST-□ is sold separately.

(MST-

											, ,		
	l open collector	BRP100- DDT	BR100- DDT	BRP400- DDT	BR400- DDT	BRP200- DDTN	BR200- DDTN	BRP3M- MDT	BR3M- MDT	BR4M- TDTD	BR20M- TDTD	BR4M- TDTL	BR20M- TDTL
		BRP100- DDT-C	BR100- DDT-C	BRP400- DDT-C	BR400- DDT-C	BRP200- DDTN-C	BR200- DDTN-C	BRP3M- MDT-C	BR3M- MDT-C	BR4M- TDTD-C	BR20M- TDTD-C	BR4M- TDTL-C	BR20M- TDTL-C
	open collector	BRP100- DDT-P BRP100-	BR100- DDT-P	BRP400- DDT-P BRP400-	BR400- DDT-P	BRP200- DDTN-P BRP200-	BR200- DDTN-P BR200-	BRP3M- MDT-P BRP3M-	BR3M- MDT-P BR3M-	BR4M- TDTD-P BR4M-	BR20M- TDTD-P BR20M-	BR4M- TDTL-P BR4M-	BR20M- TDTL-P BR20M-
			DDT-C-P				DDTN-C-P		MDT-C-P				TDTL-C-P
Case		Plastic	Metal	Plastic	Metal	Plastic	Metal	Plastic	Metal	Metal			
Sensing type		Diffuse reflective type Narrow beam reflective type					Retroreflective type Through-beam type						
Sensing distance		100mm*	100mm ^{×1} 400mm ^{×2} 200mm ^{×2} 3m ^{×3} 4m 20m 4m 20m						20m				
	g target	Opaque, translucent materials of min. Ø60mm Opaque materials of min. Ø15mm										mm	
Hysteresis Response time			Max. 20% at rated sensing distance										
Respor Power		Max. 1m	is)C==±10%	(rinnla	D D. may	10%)							
	supply t consumption				-r max.	1070)							
Light source			Max. 45mA Infrared LED (940nm) Infrared LED (850nm) Red LED (660nm) Infrared LED (850nm)										
Sensitivity adjustment		Sensitivity adjuster [Red LED (000nm)]Initiated LED (000nm)								.,			
	ion mode				k ON bv	control wir	e (white)			Dark ON		Light ON	
Control	beration mode Selectable Light ON or Dark ON by control wire (white) Dark ON Light ON phtrol output NPN or PNP open collector output •Load voltage: max. 30VDC •Load current: max. 200mA •Residual voltage - NPN: max. 1VDC, PNP: max. 2.5VDC								ax. 2.5VDC				
Protect	ion circuit					rcuit, outpu							
ndicate						r indicator:	red LED (o	only for ei	mitter of t	hrough-bea	am type)		
Connec			pe, conne										
Insulation resistance Noise immunity		Over 20MΩ (at 500VDC megger)											
		±240V the square wave noise (pulse width: 1μs) by the noise simulator 1000VAC 50/60Hz for 1 minute											
Dielectric strength Vibration		1.5mm amplitude at frequency of 10 to 55Hz (for 1 min) in each X, Y, Z direction for 2 hours											
Shock	// 1		500m/s ² (approx. 50G) in each X, Y, Z direction for 3 times										
-	iont illumination												
ĕ⊢—	Ambient illumination Sunlight: max. 11,000lx, incandescent lamp: max. 3,000lx (receiver illumination) Ambient temperature -10 to 60°C, storage: -25 to 75°C Ambient humidity 35 to 85%RH, storage: 35 to 85%RH												
≣ Amb													
Protect	tion structure	IP66 (IE	C standa	rd) (BR20	M Series	: IP67)							
Material		 Case - BRP: polyamide (black) BR: brass, ni-plate Sensing part - polycarbonate lens 							le (black) s, ni-plate g part -				
Cable	Cable type	Ø5mm, 4-wire, 2m (emitter of through-beam type: Ø5mm, 2-wire, 2m / receiver: Ø5mm, 3-wire, 2m) (AWG22, core diameter: 0.08mm, number of cores: 60, insulator out diameter: Ø1.25mm)											
	Connector type	M12 connector											
Acce-	Individual	Adjustment screwdriver Screwdriver, Reflector (MS-2)											
ssory	Common	 BRP: I 	18 fixing M18 fixing		asher: 1			·			8 fixing nut 18 fixing n		er: 2
Approv	al	CE											
Neight	*4		pprox. 14 : approx.				approx. 160 : approx. 9			•BR: appr •BR-C: ap	ox. 340g (a prox. 150g		

×1: Non-glossy white paper 50×50mm. ※2: Non-glossy white paper 100×100mm.

*3: The sensing distance is specified with using the MS-2 reflector. The distance between the sensor and the reflector should be set over

0.1m. When using reflective tapes, the reflectivity will vary by the size of the tape. Please refer to the catalog or website. ※4: The weight includes packaging. The weight in parenthesis is for unit only.

% Tightening torque for connector is 0.39 to 0.49N⋅m.

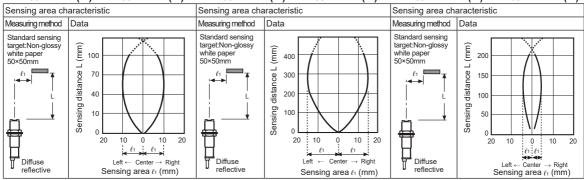
The temperature or humidity mentioned in Environment indicates a non freezing or condensation.



Feature Data

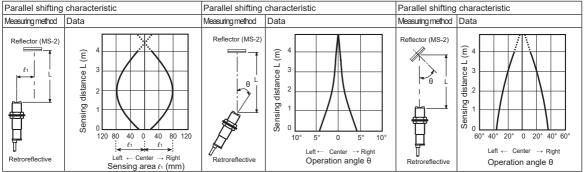
◎ Diffuse reflective type / Narrow beam reflective type ●BR100-DDT-□(-P)/BRP100-DDT-□(-P) ●BR400-DDT-□(-P)/BRP400-DDT-□(-P)

•BR200-DDTN- (-P)/BRP200-DDTN- (-P)

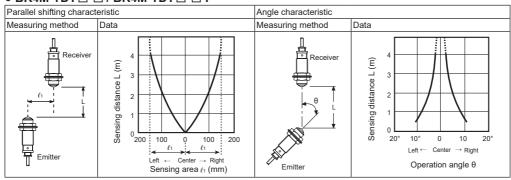


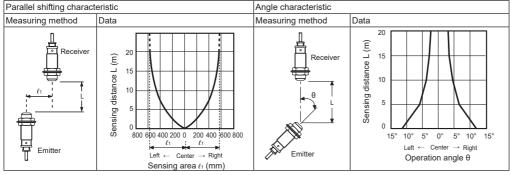
© Retroreflective type

BR3M-MDT-□(-P) / BRP3M-MDT-□(-P)

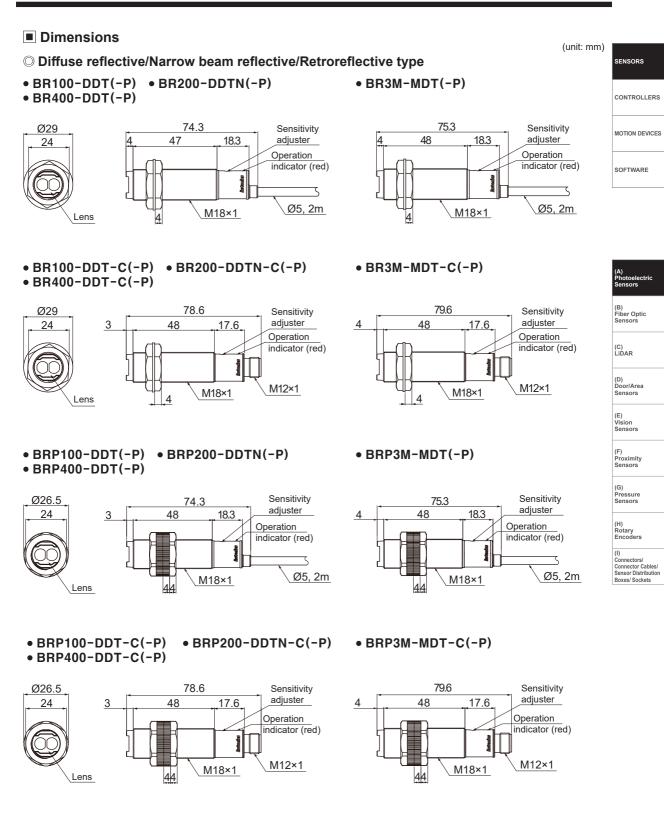


© Through-beam type ● BR4M-TDT□-□ / BR4M-TDT□-□-P

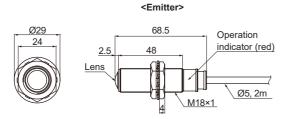




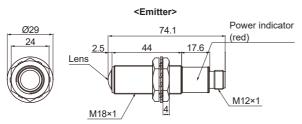
Autonics



- Through-beam type
- BR4M-TDTD(-P) / BR4M-TDTL(-P)

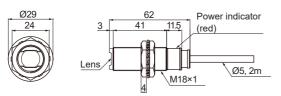


• BR4M-TDTD-C(-P) / BR4M-TDTL-C(-P)

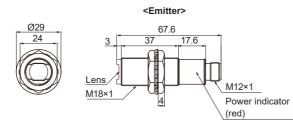


• BR20M-TDTD(-P) / BR20M-TDTL(-P)

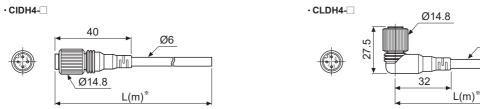
<Emitter>



• BR20M-TDTD-C(-P) / BR20M-TDTL-C(-P)

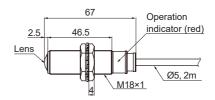


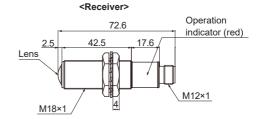
• Connection cable (sold separately)



%Specifi cation of connector cable: Ø6mm, 4-wire, 2m/3m/5m/7m

(AWG22, core diameter: 0.08mm, number of cores: 60, insulator out diameter: Ø1.65mm)





3 41 11.5 Operation indicator (red)

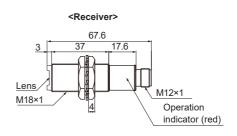
M18×1

Ø5, 2m

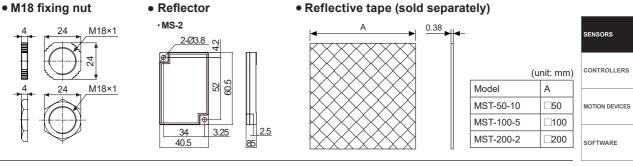
Ø6

<Receiver>

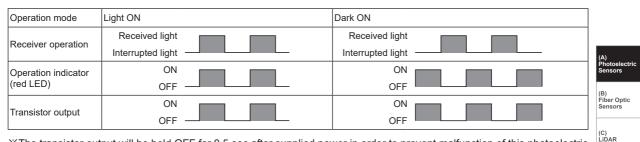
Lens



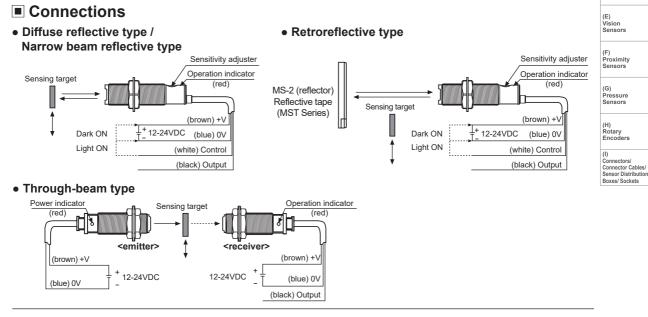
Cylindrical Type



Operation Mode



* The transistor output will be held OFF for 0.5 sec after supplied power in order to prevent malfunction of this photoelectric sensor (except through-beam type).



Connections for Connector Part



	Cable color	Application					
Pin No.		Diffuse/	Through-beam type				
		Narrow beam reflective/ Retroreflective type	Emitter	Receiver			
1	Brown	24VDC	24VDC	24VDC			
2	White	CONTROL	N·C	GND			
3	Blue	GND	GND	GND			
4	Black	OUTPUT	N·C	OUTPUT			

• Connector cable (sold separately) ※Please refer to the

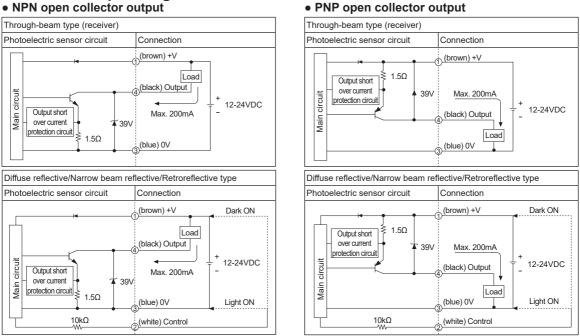
connector cable section.

M12 Connector pin

Autonics

Sensors

Control Output Diagram



*Before using this unit, select Light ON/Dark ON with control wire. (light on: connect control wire 0V / dark on: connect control wire with +V) *Control wire is only for Diffuse reflective/Narrow beam reflective/Retroreflective type.

%If short-circuit the control output terminal or supply current over the rated specification, normal control signal is not output due to the output short over current protection circuit.

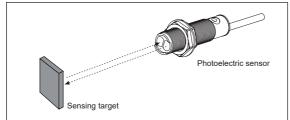
Installation and Sensitivity Adjustment

Install the sensor to the desired place and check the connections. Supply the power to the sensor and adjust the optical axis and the sensitivity as following.

When using photoelectric sensors closely over two units, it may result in malfunction due to mutual interference. When installing the product, tighten the screw with a tightening torque of 0.39N m for BRP and to 14.7N m for BR.

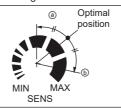
O Diffuse reflective/Narrow beam reflective type

1. The sensitivity should be adjusted depending on a sensing target or mounting place.



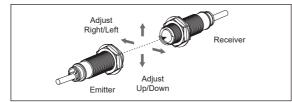
- 2. Set the target at a position to be detected by the beam, then turn the sensitivity adjuster until position (a) where the operation indicator turns ON from min. position of the sensitivity adjuster.
- 3. Take the target out of the sensing area, then turn the sensitivity adjuster until position (b) where the operation indicator turns ON. If the indicator dose not turn ON, max. position is b.
- 4. Set the sensitivity adjuster at the center of two switching position (a), (b).

XBe sure that it can be different by size, surface and gloss of target.



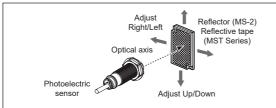
O Through-beam type

- Supply the power to the photoelectric sensor, after setting the emitter and the receiver facing each other.
- Set the receiver in center of position in the middle of the operation range of indicator by adjusting the receiver or the emitter right and left, up and down.
- 3. After the adjustment, check the stability of operation putting the object at the optical axis.
- ※If the sensing target is translucent body or smaller than Ø15, it can be missed by sensor cause light penetrate it.

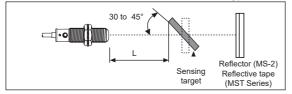


© Retroreflective type

- Supply the power to the photoelectric sensor, after setting the photoelectric sensor and the reflector (MS-2) or reflective tape face to face.
- Set the photoelectric sensor in the position which indicator turns on, as adjusting the reflector or the sensor right and left, up and down.
- 3. Fix both units tightly after checking that the unit detects the target.



- XIf using more than 2 photoelectric sensors in parallel, the space among them should be more than 30cm.
- XII reflectance of target is higher than non-glossy white paper, it might cause malfunction by reflection from the target when the target is near to photoelectric sensor. Therefore put enough space between the target and the photoelectric sensor or the surface of the target should be installed at angle of 30 to 45° against optical axis. (when a sensing target with high reflectance near by, photoelectric sensing with the polarizing filter should be used.)
- Sensitivity adjustment: Refer to the diffuse reflective/ narrow beam reflective type's.



- %If the mounting place is too narrow, please use MS-4 instead of MS-2.
- ※Please use reflective tape (MST Series) for where a reflector is not installed.



Reflectivity by Reflective Tape Model

MST-50-10 (50×50mm)	80%]	
MST-100-5 (100×100mm)	120%		CONTROLL
MST-200-2 (200×200mm)	140%]	

%This reflectivity is based on the reflector (MS-2).

※Reflectivity may vary depending on usage environment and installation conditions.

The sensing distance and minimum sensing target size increase as the size of the tape increases.

Please check the reflectivity before using reflective tapes.

%For using reflective tape, installation distance should be min. 20mm.



SOFTWARE

A) Photoelectric Sensors

Fiber Optic Sensors

(C) LiDAR

(D) Door/Area Sensors

(E) Vision Sensors

(F) Proximity Sensors

(G) Pressure Sensors

(H) Rotary Encoders

(I) Connectors/ Connector Cables/ Sensor Distributior Boxes/ Sockets