2-phase Stepper Motor

AK-2 Series INSTRUCTION MANUAL

TCD210131AC

Autonics

Thank you for choosing our Autonics product.

Read and understand the instruction manual and manual thoroughly before using the product.

For your safety, read and follow the below safety considerations before using. For your safety, read and follow the considerations written in the instruction manual, other manuals and Autonics website.

Keep this instruction manual in a place where you can find easily.

The specifications, dimensions, etc. are subject to change without notice for product improvement. Some models may be discontinued without notice.

Follow Autonics website for the latest information.

Safety Considerations

- Observe all 'Safety Considerations' for safe and proper operation to avoid hazards.
- A symbol indicates caution due to special circumstances in which hazards may occur.

★ Warning Failure to follow instructions may result in serious injury or death.

- 01. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss. (e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime / disaster prevention devices, etc.)
- Failure to follow this instruction may result in personal injury, economic loss or fire.

 10. Do not use the unit in the place where flammable / explosive / corrosive gas, high humidity, direct sunlight, radiant heat, vibration, impact or salinity may be present. iction may result in explosion or fire
- 03. Fix the unit on the metal plate.
- Failure to follow this instruction may result in personal injury or product and ambient equinment damage
- 04. Do not connect, repair, or inspect the unit while connected to a power source. re to follow this instruction may result in fire
- 05. Install the unit after considering counter plan against power failure. illure to follow this instruction may result in personal injury, economic loss or fire.
- 06. Check 'Connections' before wiring.
- 07. Do not disassemble or modify the unit.
- re to follow this instruction may result in fire or electric shock. 08. Install the motor in the housing or ground it.
- ailure to follow this instruction may result in personal injury, fire or electronic shock.
- 09. Make sure to install covers on motor rotating components.
- 10. Do not touch the unit during or after operation for a while. ilure to follow this instruction may result in burn due to high temperature of the surface.
- 11. Upon occurrence of an error, disconnect the power source.
- Failure to follow this instruction may result in personal injury, fire or electronic shock.

▲ Caution Failure to follow instructions may result in injury or product damage.

- 01. Use the unit within the rated specifications.
- ailure to follow this instruction may result in fire or product damage 02. Use a dry cloth to clean the unit, and do not use water or organic solvent.

- 03. The motor may overheat depending on the environment Install the unit at the well-ventilated environment and forced cooling with a cooling fan. this instruction may result in product damage or deg
- 04. Keep the product away from metal chip, dust, and wire residue which flow into the unit. illure to follow this instruction may result in fire or product damage

Cautions during Use

- · Follow instructions in 'Cautions during Use'.
- Otherwise, it may cause unexpected accidents
- · At low temperature, reducing the grease's consistency of ball-baring and etc. causes the friction torque increment.
- Start the motor gradually since motor's torque is in normal state.
- Maintain and inspect regularly the following lists.
- Unwinding bolts and connection parts for the unit installation and load connection Abnormal sound from ball-bearing of the unit
- Damage and stress of lead cable of the unit
- Connection error with driver
- Inconsistency between the axis of motor output and the center, concentric (eccentric.) declination) of the load, etc.
- This unit may be used in the following environments.
- Indoors (in the environment condition rated in 'Specifications')
- Altitude max. 2,000 m
- Pollution degree 2
- Installation category II

Cautions during Installation

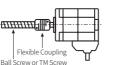
- Follow instructions in 'Safety Considerations' and 'Cautions during Use'
- Otherwise, it may cause unexpected accidents.
- Install the motor in a place that meets the certain conditions specified below. It may cause product damage if it is used out of following conditions. - Inside of the housing which is installed indoors
- (This unit is designed/manufactured for the purpose of attaching to equipment. Install a ventilation device.)
- The place without contact with water, oil, or other liquid
- The place without contact with strong alkali or acidity
- The place with less electronic noise occurs by welding machine, motor, etc.
- The place where no radioactive substances and magnetic fields exist. It shall be no vacuum
- Motor can be installed horizontally and vertically. Refer to 'Shaft Allowable Load along Installation Direction!
- If a force (30 N) exceeding the specification is applied to the motor cable during installation, it may cause the contact failure and disconnection. If the excessive force or frequent cable movement is required, establish safety measures
- In consideration of heat dissipation and vibration prevention, mount the motor as tight as possible against a metal panel with high thermal conductivity such as iron or alumin

Cautions during Connection with Load

- Do not disassemble or modify the motor shaft to connect with the load.
- Tighten the screw not to be unscrewed when connecting with load.
- · Refer to 'Shaft Allowable Load along Installation Direction' and take care of potential shock when connecting with load.
- Connect the motor shaft and the load shaft to be parallel.
- If the center with the load is not aligned with the shaft, it may cause unexpected accidents such as severe vibration, shorten life cycle of the shaft bearing and shaft damage.
- When attaching coupling or pulley with motor shaft, be aware of damage on motor shaft and shaft bearing

■ Pulley, belt, wire ■ Gear









When connecting the load directly to the motor shaft, use a flexible coupling (ERB

Connect the motor shaft and the line which connects the center of two pulleys to be

0

Connect the motor shaft to the center of gear teeth to be interlocked

6

Ordering Information

0

1 Max. stop torque

This is only for reference, the actual product does not support all combinations.. For selecting the specified model, follow the Autonics website.







§ Frame size 4: 42 mm

2 Rated current

M: 1.2 A / Phase

G: 2.0 A / Phase Motor phase

2: 2-phase

6: 🗌 56 mm

8

Axial length

Number: Refer to 'Dimensions

4

6

⑤ Shaft type No mark: Single shaft W: Dual shaft

Product Components

- Product
- Instruction manual
- Motor cable: CID6-AK42, CID6-AK56

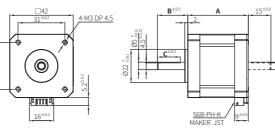
Sold Separately

- Motor cable: CID6-AK42, CID6-AK56
- Flexible coupling: ERB Series

Dimensions

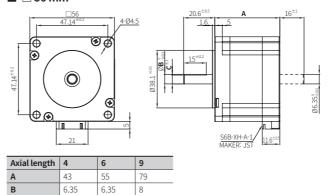
- Unit: mm, For the detailed drawings, follow the Autonics website.
- · The dotted lines are included in dual shaft type.

■ □ 42 mm



Axial length	3	4	5
Α	34	40	48
В	20	20	23
С	15	15	18

■ □ 56 mm



Panel Cut-out Dimensions

5.85

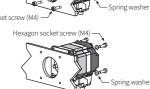
■ □ 42 mm

5.85









Shaft Allowable Load along Installation Direction

Horizontal installation Vertical installation

Frame size		Horizontal installation: Overhung Allowable load [N]			Vertical installation: Thrust Allowable load [N]	
	D=0	D=5	D=10	D=15	I nrust Allowable load [N]	
☐ 42 mm	20	25	33	51	- Under load of motor	
□ 56 mm	53	66	87	127	Unitide toad of Motor	

Specifications

Model	A2K-M243□	A3K-M244□	A4K-M245□	
Max. stop torque	2.06 kgf cm (0.21 N m)	2.97 kgf cm (0.3 N m)	3.3 kgf cm (0.33 N m)	
Rotor inertia moment	33×10^{-7} kg \cdot m ²	56×10 ⁻⁷ kg · m ²	72×10 ⁻⁷ kg · m²	
Rated current	1.2 A / Phase			
Basic step angle	1.8° / 0.9° (Full step / Half step)			
Resistance	$2.7 \Omega \pm 10\%$ $3.3 \Omega \pm 10\%$ $2.8 \Omega \pm 10$		$2.8~\Omega~\pm~10\%$	
Inductance	$2.3\mathrm{mH}\pm20\%$	$3.3\mathrm{mH}\pm20\%$	$3.1\mathrm{mH}\pm20\%$	
Unit weight (packaged)	\approx 0.23 kg (\approx 0.33 kg)	\approx 0.29 kg (\approx 0.39 kg)	\approx 0.43 kg (\approx 0.53 kg)	

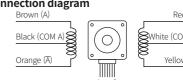
Model	A6K-G264□	A9K-G265□	A16K-G268□	
Max. stop torque	5.7 kgf cm (0.57 N m)	9.0 kgf cm (0.90 N m)	15.70 kgf cm (1.57 N m)	
Rotor inertia moment	145×10⁻⁻kg · m²	245×10 ⁻⁷ kg · m ²	470×10 ⁻⁷ kg · m ²	
Rated current	2.0 A / Phase			
Basic step angle	1.8° / 0.9° (Full step / Half step)			
Resistance	1.3 Ω ± 10% 1.7 Ω ± 10% 2.5 Ω ± 10			
Inductance	$1.7\mathrm{mH}\pm20\%$	3.0 mH ± 20%	4.9 mH ± 20%	
Unit weight (packaged)	\approx 0.50 kg (\approx 0.65 kg)	$\approx 0.70 \text{ kg} (\approx 0.85 \text{ kg})$	$\approx 1.10 \text{ kg} (\approx 1.25 \text{ kg})$	

Motor phase	2-phase
Run method	Unipolar
Insulation class	B type (130°C)
Insulation resistance	Between the charging part and the case: \geq 100 M Ω (500 VDC= megger)
Dielectric strength	Between the charging part and the case: 500 VAC \sim 50 / 60 Hz for 1 min
Ambient temp.	0 to 50°C, storage: -20 to 70°C (no freezing or condensation)
Ambient humi.	20 to 90%RH, storage: 15 to 90%RH (no freezing or condensation)
Protection rating	IP30 (IEC34-5 standard)
Certification	EHC
Stop angle error	≤ 0.05° (Full step, no load)
Shaft vibration	0.05 mm T.I.R.
Radial movement 01)	\leq 0.05 mm T.I.R.
Axial movement 02)	\leq 0.075 mm T.I.R.
Shaft concentricity	0.075 mm T.I.R.
Shaft perpendicularity	0.075 mm T.I.R.

02) Amount of axial shaft displacement when applying axial load (10 N) to the shaft.

Connection

■ Inner connection diagram



Connector

Pin numbe	Pin number 01)		Function
□ 42 mm	□ 56 mm	Cable color	runction
4	1	Brown	А
5	2	Black	COM A
1	3	Orange	Ā
6	4	Red	В
2	5	White	COM B
3	6	Yellow	B

01) The number is based on when facing motor's axis

	Connector specification					
	Туре		□ 42 mm		□ 56 mm	
			Model	Manufacturer	Model	Manufacture
- 1	Motor part	HOUSING	S6B-PH-K	JST	S6B-XH-A-1	JST
	Cable part	HOUSING	PHR-6	JST	XHP-6	JST
		TERMINIAL	SPH-002T-P0 5S	IST	SXH-001T-P0.6	IST

Cable specification		
☐ 42 mm	□ 56 mm	
III 1007 ΔWG 24 320 mm	LIL 1007 AWG 22 400 mm	

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