## 20 mm Diameter Incremental Rotary Encoders

# **E20 Series**

# **INSTRUCTION MANUAL**

TCD210017AA

**Autonics** 

Thank you for choosing our Autonics product.

Read and understand the instruction manual and manual thoroughly before using the product.

For your safety, read and follow the below safety considerations before using. For your safety, read and follow the considerations written in the instruction manual, other manuals and Autonics website.

Keep this instruction manual in a place where you can find easily.

The specifications, dimensions, etc. are subject to change without notice for product improvement. Some models may be discontinued without notice.

Follow Autonics website for the latest information.

#### **Safety Considerations**

- Observe all 'Safety Considerations' for safe and proper operation to avoid hazards.
- A symbol indicates caution due to special circumstances in which hazards may occur.

★ Warning Failure to follow instructions may result in serious injury or death.

- 01. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss. (e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime / disaster prevention devices, etc.) ailure to follow this instruction may result in personal injury, economic loss or fire.
- 02. Do not use the unit in the place where flammable / explosive / corrosive gas, high humidity, direct sunlight, radiant heat, vibration, impact or salinity may be present.

re to follow this instruction may result in explosion or fire.

03. Install on a device panel to use. Failure to follow this instruction may result in fire.

- 04. Do not connect, repair, or inspect the unit while connected to a power source.
- Failure to follow this instruction may result in fire.
- 05. Check 'Connections' before wiring. ailure to follow this instruction may result in fire
- 06. Do not disassemble or modify the unit.

Failure to follow this instruction may result in fire

▲ Caution Failure to follow instructions may result in injury or product damage.

- 01. Use the unit within the rated specifications.
  - ailure to follow this instruction may result in fire or product damage.
- 02. Do not short the load.
- ailure to follow this instruction may result in fire
- 03. Do not use the unit near the place where there is the equipment which generates strong magnetic force or high frequency noise and strong alkaline, strong acidic exists.

Failure to follow this instruction may result in product damage.

#### **Cautions during Use**

- Follow instructions in 'Cautions during Use'.
- Otherwise, It may cause unexpected accidents.
- 5 VDC==, 12 VDC== power supply should be insulated and limited voltage / current or Class 2. SELV power supply device.
- For using the unit with the equipment which generates noise (switching regulator, inverter, servo motor, etc.), ground the shield wire to the F.G. terminal.
- Ground the shield wire to the F.G. terminal.

  When supplying power with SMPS, ground the F.G. terminal and connect the noise canceling capacitor between the 0 V and F.G. terminals.
- Wire as short as possible and keep away from high voltage lines or power lines, to prevent inductive noise.
- For Line driver unit, use the twisted pair wire which is attached seal and use the receiver for RS-422A communication.
- Check the wire type and response frequency when extending wire because of distortion of waveform or residual voltage increment etc. by line resistance or capacity between lines.
- This unit may be used in the following environments.
- Indoors (in the environment condition rated in 'Specifications') - Altitude max. 2,000 m
- Pollution degree 2
- Installation category II

#### **Cautions during Installation**

- $\bullet$  Install the unit correctly with the usage environment, location, and the designated
- specifications.

   Do not load overweight on the shaft.
- Do not put strong impact when insert a coupling into shaft.
- Failure to follow this instruction may result in product damage.  $\bullet$  When fixing the product or coupling with a wrench, tighten under 0.15 N m.
- If the coupling error (parallel misalignment, angular misalignment) between the shaft increases while installation, the life cycle of the coupling and the encoder can be
- Do not apply tensile strength over 15 N to the cable.

### **Ordering Information**

This is only for reference, the actual prodcut does not support all combinations. For selecting the specified model, follow the Autonics website.

E20 **0 2** - **3** - **4** - **5** - **6** 

Shaft type

S: Shaft type HB: Hollow Built-in type

N: NPN open collector output V: Voltage output L: Line driver output O Power supply

5:5 VDC== ±5%

**7** Connection

12: 12 VDC== ±5%

**⊙** Control output

2 Shaft outer diameter / Shaft inner diameter

2: Ø 2 mm 2.5: Ø 2.5 mm

Resolution Number: Refer to resolution in 'Specifications'

R: Axial cable type S: Radial cable type

Output phase

6: A,  $\overline{A}$ , B,  $\overline{B}$ , Z,  $\overline{Z}$ 

3: Ø 3 mm

## **Product Components**

Shaft type	Shaft type	Hollow Built-in type	
<b>Product Components</b>	Product, Instruction manual		
Bolt	× 4	× 2	
Coupling	×1	-	
Bracket	-	×1	

## Connections

- Unused wires must be insulated.
- The metal case and shield cable of encoders must be grounded (F.G.).
- F.G. (Frame Ground) must be grounded separately.

#### ■ NPN open collector / Voltage output

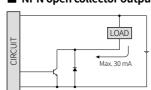
Color	Function	Color	Function
Black	OUT A	Brown	+V
White	OUT B	Blue	GND
^	OUT 7	ci · i i	F.C.

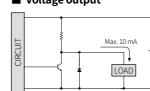
Color	Function	Color	Function
Black	OUTA	Orange	OUT Z
Red	OUT Ā	Yellow	OUT Z
White	OUT B	Brown	+V
Gray	OUT B	Blue	GND
Shield	F.G.	_	-

#### Inner Circuit

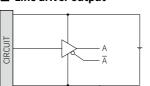
• Output circuits are identical for all output phase.

■ NPN open collector output ■ Voltage output





#### ■ Line driver output

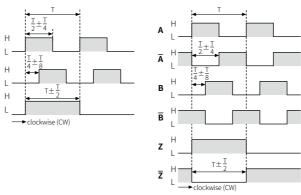


#### **Output Waveform**

- The rotation direction is based on facing the shaft, and it is clockwise (CW) when rotating to the right.
- Phase difference between A and B:  $\frac{1}{4} \pm \frac{1}{8}$  (T = 1 cycle of A)

### ■ NPN open collector / Voltage output

■ Line driver output



#### **Specifications**

Model	E20	E20	E20
Resolution	100 / 200 / 320 / 360 PPR model		
Control output	NPN open collector output	Voltage output	Line driver output
Output phase	A, B, Z	A, B, Z	$A, \overline{A}, B, \overline{B}, Z, \overline{Z}$
Inflow current	≤ 30 mA	-	≤ 20 mA
Residual voltage	≤ 0.4 VDC==	≤ 0.4 VDC==	≤ 0.5 VDC==
Outflow current	=	≤ 10 mA	≤ -20 mA
Output voltage	-	-	≥ 2.5 VDC==
Response speed 01)	≤1μs ≤0.5μs		≤ 0.5 µs
Max. response frequency	100 kHz		
Max. allowable revolution 02)	6,000 rpm		
Starting torque	$\leq$ 5 $\times$ 10 <sup>4</sup> N m		
Inertia moment	$\leq 0.5 \mathrm{g\cdot cm^2} (5 \times 10^8 \mathrm{kg\cdot m^2})$		
Allowable shaft load	Radial: ≤ 200 gf, Thrust: ≤ 200 gf		
Unit weight	≈ 35 g		
Approval	C € EHI	C € EHI	EAC
01) Based on cable length: 1 m. I sink: 20 mA			

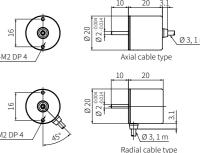
02) Select resolution to satisfy Max. allowable revolution ≥ Max. response revolution  $[max. response revolution (rpm) = \frac{max. response frequency}{resolution} \times 60 sec]$ 

Model	E20	E20	E20□□-□-6-L-5-□
Power supply	5 VDC== ± 5% (ripple P-P: ≤ 5%) / 12 VDC== ± 5% (ripple P-P: ≤ 5%) model		5 VDC== ± 5% (ripple P-P: ≤ 5%)
Current consumption	≤ 60 mA (no load)		≤ 50 mA (no load)
Insulation resistance	Between all terminals and case: ≥ 100 MΩ (500 VDC= megger)		
Dielectric strength	Between all terminals and case: 500 VAC~ 50 / 60 Hz for 1 minute		
Vibration	$1~\rm{mm}$ double amplitude at frequency 10 to 55 Hz (for 1 minute) in each X, Y, Z direction for 2 hours		
Shock	≲ 50 G		
Ambient temp.	-10 to 70 °C, storage: -20 to 80 °C (no freezing or condensation)		
Ambient humi.	35 to 85%RH, storage: 35 to 90%RH (no freezing or condensation)		
Protection rating	IP50 (IEC standard)		
Connection	Axial / Radial cable type model		
Cable spec.	Ø 3 mm, 5-wire (Line driver output: 8-wire), 1 m, shield cable		

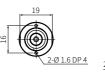
#### Dimensions

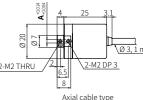
• Unit: mm, For the detailed drawings, follow the Autonics website

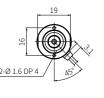
#### ■ Shaft type

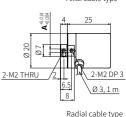


## ■ Hollow Built-in type



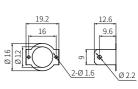






	Α
20HB2	Ø2
20HB2.5	Ø 2.5
20HB3	Ø3

## ■ Bracket



#### ■ Coupling



- Parallel misalignment: ≤ 0.15 mm
- Angular misalignment: ≤ 2°
  End-play: ≤ 0.2 mm

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