#### 40 mm Diameter Incremental Rotary Encoders

# **E40 Series**

# **INSTRUCTION MANUAL**

TCD210019AA

**Autonics** 

Thank you for choosing our Autonics product.

Read and understand the instruction manual and manual thoroughly before using the product.

For your safety, read and follow the below safety considerations before using. For your safety, read and follow the considerations written in the instruction manual, other manuals and Autonics website.

Keep this instruction manual in a place where you can find easily.

The specifications, dimensions, etc. are subject to change without notice for product improvement. Some models may be discontinued without notice.

Follow Autonics website for the latest information.

#### **Safety Considerations**

- Observe all 'Safety Considerations' for safe and proper operation to avoid hazards.
- A symbol indicates caution due to special circumstances in which hazards may occur.

★ Warning Failure to follow instructions may result in serious injury or death.

- 01. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss. (e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime / disaster prevention devices, etc.) ailure to follow this instruction may result in personal injury, economic loss or fire
- 02. Do not use the unit in the place where flammable / explosive / corrosive gas, high humidity, direct sunlight, radiant heat, vibration, impact or salinity may be present.

re to follow this instruction may result in explosion or fire.

03. Install on a device panel to use. ailure to follow this instruction may result in fire.

04. Do not connect, repair, or inspect the unit while connected to a power

source.

Failure to follow this instruction may result in fire.

05. Check 'Connections' before wiring. ailure to follow this instruction may result in fire

06. Do not disassemble or modify the unit.

Failure to follow this instruction may result in fire

⚠ Caution Failure to follow instructions may result in injury or product damage.

01. Use the unit within the rated specifications.

ailure to follow this instruction may result in fire or product damage.

02. Do not short the load.

ailure to follow this instruction may result in fire

03. Do not use the unit near the place where there is the equipment which generates strong magnetic force or high frequency noise and strong alkaline, strong acidic exists.

Failure to follow this instruction may result in product damage.

#### **Cautions during Use**

- Follow instructions in 'Cautions during Use'.
- Otherwise, It may cause unexpected accidents.
- 5 VDC==, 12 24 VDC== power supply should be insulated and limited voltage / current or Class 2, SELV power supply device.
- · For using the unit with the equipment which generates noise (switching regulator, inverter, servo motor, etc.), ground the shield wire to the F.G. terminal.
- Ground the shield wire to the F.G. terminal.
  When supplying power with SMPS, ground the F.G. terminal and connect the noise canceling capacitor between the 0 V and F.G. terminals.
- Wire as short as possible and keep away from high voltage lines or power lines, to
- prevent inductive noise. • For Line driver unit, use the twisted pair wire which is attached seal and use the
- receiver for RS-422A communication. • Check the wire type and response frequency when extending wire because of distortion of waveform or residual voltage increment etc. by line resistance or capacity
- between lines. This unit may be used in the following environments.
- Indoors (in the environment condition rated in 'Specifications')
- Altitude max. 2,000 m - Pollution degree 2
- Installation category II

#### **Cautions during Installation**

- Install the unit correctly with the usage environment, location, and the designated specifications.
- · Do not load overweight on the shaft.
- Do not put strong impact when insert a coupling into shaft.
- Failure to follow this instruction may result in product damage
- When fixing the product or coupling with a wrench, tighten under 0.15 N m.
- If the coupling error (parallel misalignment, angular misalignment) between the shaft increases while installation, the life cycle of the coupling and the encoder can be
- Do not apply tensile strength over 30 N to the cable.

#### **Ordering Information**

This is only for reference, the actual prodcut does not support all combinations.

Tot selecting the specified model, follow the Automics website.												
E40	0	0	-	8	-	4	-	6	-	6	-	0

#### Shaft type

S: Shaft type H: Hollow type

HB: Hollow Built-in type

2 Shaft outer diameter /

Shaft inner diameter

#### G Control output T: Totem pole output

N: NPN open collector output V: Voltage output L: Line driver output

O Power supply 5:5 VDC== ±5%

Connection

24: 12 - 24 VDC= ±5%

No mark: Radial cable type C: Radial cable connector type

#### 12: Ø 12 mm Resolution

6: Ø 6 mm

8: Ø 8 mm

10: Ø 10 mm

Number: Refer to resolution in 'Specifications'

### Output phase

3: A. B. Z

 $4: A, \overline{A}, B, \overline{B}$ 6: A,  $\overline{A}$ , B,  $\overline{B}$ , Z,  $\overline{Z}$ 

#### **Product Components**

Shaft type	Shaft type	Hollow type	Hollow Built-in type	
<b>Product Components</b>	Product, Instruction manual	Product (+ bracket), Instruction manual		
Bolt	× 4	× 2	× 2	
Coupling	× 1	-	-	

#### **Sold Separately**

• Connector cable: CID6S-□, CID9S-□

#### Connections

- · Unused wires must be insulated.
- The metal case and shield cable of encoders must be grounded (F.G.).
- F.G. (Frame Ground) must be grounded separately.

#### ■ Totem pole / NPN open collector / Voltage output

Pin	Color	Function	Pin	Color	Function
1	Black	OUTA	4	Brown	+V
2	White	OUTB	5	Blue	GND
3	Orange	OUTZ	6	Shield	F.G.



#### ■ Line driver output

Pin	Color	Function	Pin	Color	Function
1	Black	OUTA	5	White	OUT B
2	Red	OUTĀ	6	Gray	OUT B
3	Brown	+V	7	Orange	OUT Z
4	Blue	GND	8	Yellow	OUT Z
			9	Shield	F.G.

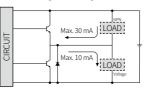
#### M17 9-pin layout



#### **Inner Circuit**

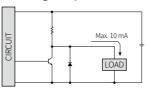
· Output circuits are identical for all output phase

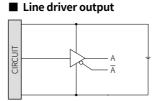
## **■** Totem pole output



# ■ NPN open collector output LOAD May 30 m/

#### ■ Voltage output



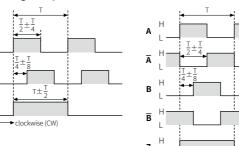


■ Line driver output

#### Output Waveform

- The rotation direction is based on facing the shaft, and it is clockwise (CW) when rotating to the right.
- Phase difference between A and B:  $\frac{1}{4} \pm \frac{1}{8}$  (T = 1 cycle of A)

#### ■ Totem pole / NPN open collector / Voltage output



E40 --- E40 --- E40 --- E40 ---

### **Specifications**

model	□- <b>T-</b> □-□	□-N-□-□	□-V-□-□	□- <b>L</b> -□-□		
Resolution	1/2/5/12 PPR <sup>(1)</sup> 10 to 5,000 PPR model					
Control output	Totem pole output	NPN open collector output	Voltage output	Line driver output		
Output phase	A, B, Z	A, B, Z	A, B, Z	$A, \overline{A}, B, \overline{B}, Z, \overline{Z}$		
Inflow current	≤ 30 mA	≤ 30 mA	-	≤ 20 mA		
Residual voltage	≤ 0.4 VDC==	≤ 0.4 VDC==	≤ 0.4 VDC==	≤ 0.5 VDC==		
Outflow current	≤ 10 mA	=	≤ 10 mA	≤ -20 mA		
Output voltage (5 VDC==)	≥ (power supply -2.0) VDC=	-	-	≥ 2.5 VDC==		
Output voltage (12 - 24 VDC==)	≥ (power supply -3.0) VDC=	-	-	≥ (power supply -3.0) VDC=		
Response speed 02)	$\leq 1 \mu s$ $\leq 0.5 \mu s$					
Max. response freq.	300 kHz					
Max. allowable revolution 03)	5,000 rpm					
Starting torque	E40S: ≤ 0.004 N m E40H, E40HB: ≤ 0.005 N m					
Inertia moment	$\leq$ 40 g·cm <sup>2</sup> (4 × 10 <sup>-6</sup> kg·m <sup>2</sup> )					
Allowable shaft load	Radial: ≤ 2 kgf, Thrust: ≤ 1 kgf					
Unit weight	≈ 120 g					
Approval	C € ERI	C € ERI	C € EHI	ERC		

- 01) Depending on the control ouput, only A, B or A, A, B, B are output.
- 02) Based on cable length: 2 m, I sink: 20 mA

03) Select resolution to satisfy Max. allowable revolution ≥ Max. response revolution [max. response revolution (rpm) =  $\frac{\text{max. response frequency}}{\text{resolution}} \times 60 \text{ sec}$ ]

#### 5 VDC== $\pm$ 5% (ripple P-P: $\leq$ 5%) / 12 - 24 VDC== $\pm$ 5% (ripple P-P: $\leq$ 5%) model Current otempole, NPN open collector, Voltage output: ≤ 80 mA (no load) ine driver output: ≤ 50 mA (no load) **Insulation resistance** Between all terminals and case: $\geq 100 \text{ M}\Omega$ (500 VDC= megger) Between all terminals and case: 750 VAC $\sim 50/60$ Hz for 1 minute mm double amplitude at frequency 10 to 55 Hz (for 1 minute) in each X, Vibration Shock -10 to 70 °C, storage: -25 to 85 °C (no freezing or condensation) Ambient temp. 35 to 85%RH, storage: 35 to 90%RH (no freezing or condensation) Ambient humi. IP50 (IEC standard)

Radial cable type / cable connector type model

able type: 2 m, cable connector type: 250 mm

Ø 5 mm, 5-wire (Line driver output: 8-wire), shield cable

AWG24 (0.08 mm, 40-core), insulator diameter: Ø 1 mm

Totempole, NPN open collector, Voltage output: M17 6-pin socket type Line driver output: M17 9-pin socket type

#### Dimensions

Connector spec.

Protection rating

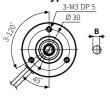
Cable spec.

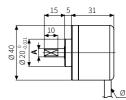
Wire spec.

Power supply

- Unit: mm, For the detailed drawings, follow the Autonics website.
- · Following items are based on cable type.
- Refer to 'Specifications' for detailed specifications of cable, wire and connector.

# ■ Shaft type



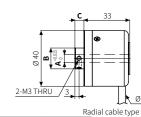


Radial cable type

Ø 6 -0.004 E40S6 Ø8 -0.005 -0.02 F40S8

# ■ Hollow type

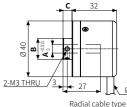




			Rau
	Α	В	С
E40H6	Ø6	Ø 15	6.5
E40H8	Ø8	Ø 15	6.5
E40H10	Ø 10	Ø 17	6.3
E40H12	Ø 12	Ø 17	6.3

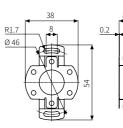
#### ■ Hollow Built-in type





С E40HB6 Ø 15 6.5 Ø6 E40HB8 Ø 15 Ø8 6.5 E40HB10 Ø 10 Ø 17 6.3 6.3 Ø 17 F40HB12 Ø 12

#### ■ Bracket





A B C D E E40S6 | Ø 6 | Ø 15 | 2.8 | 22 | 4-M3 E40S8 Ø8 Ø19 3.4 25 4-M4

- Angular misalignment: ≤ 5°
  End-play: ≤ 0.5 mm