58 mm Diameter Absolute Single-Turn **Rotary Encoders (Optical)** 

# **EP58 Series INSTRUCTION MANUAL**

TCD210035AA

Autonics

Thank you for choosing our Autonics product.

Read and understand the instruction manual and manual thoroughly before using the product.

For your safety, read and follow the below safety considerations before using. For your safety, read and follow the considerations written in the instruction manual, other manuals and Autonics website.

Keep this instruction manual in a place where you can find easily. The specifications, dimensions, etc. are subject to change without notice for product improvement. Some models may be discontinued without notice. Follow Autonics website for the latest information.

Safety Considerations

• Observe all 'Safety Considerations' for safe and proper operation to avoid hazards.

• A symbol indicates caution due to special circumstances in which hazards may occur.

**Warning** Failure to follow instructions may result in serious injury or death.

- 01. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss. (e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime / disaster prevention devices, etc.) ailure to follow this instruction may result in personal injury, economic loss or fire.
- 02. Do not use the unit in the place where flammable / explosive / corrosive gas, high humidity, direct sunlight, radiant heat, vibration, impact or salinity may be present. ilure to follow this instruction may result in explosion or fire.

03. Install on a device panel to use.

Failure to follow this instruction may result in fire. 04. Do not connect, repair, or inspect the unit while connected to a power source.

Failure to follow this instruction may result in fire. 05. Check 'Connections' before wiring. ailure to follow this instruction may result in fire

06. Do not disassemble or modify the unit. Failure to follow this instruction may result in fire

▲ Caution Failure to follow instructions may result in injury or product damage.

- 01. Use the unit within the rated specifications.
- ailure to follow this instruction may result in fire or product damage. 02. Do not short the load. ailure to follow this instruction may result in fire
- 03. Do not use the unit near the place where there is the equipment which generates strong magnetic force or high frequency noise and strong alkaline, strong acidic exists.

Failure to follow this instruction may result in product damage.

# **Cautions during Use**

• Follow instructions in 'Cautions during Use'.

- Otherwise, It may cause unexpected accidents • 5 VDC==, 12 - 24 VDC== power supply should be insulated and limited voltage / current
- or Class 2, SELV power supply device.
  For using the unit with the equipment which generates noise (switching regulator, inverter, servo motor, etc.), ground the shield wire to the F.G. terminal.
- Ground the shield wire to the F.G. terminal.
- When supplying power with SMPS, ground the F.G. terminal and connect the noise
- canceling capacitor between the 0 V and F.G. terminals. • Wire as short as possible and keep away from high voltage lines or power lines, to
- prevent inductive noise. · Check the wire type and response frequency when extending wire because of
- distortion of waveform or residual voltage increment etc. by line resistance or capacity between lines.
- This unit may be used in the following environments. - Indoors (in the environment condition rated in 'Specifications')
- Altitude max. 2.000 m
- Pollution degree 2
- Installation category II

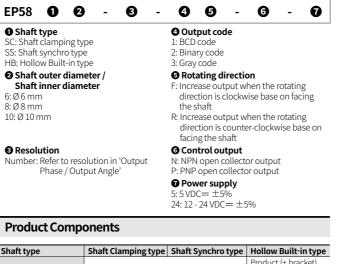
# **Cautions during Installation**

- Install the unit correctly with the usage environment, location, and the designated specifications. • Do not load overweight on the shaft.
- · Do not put strong impact when insert a coupling into shaft.
- Failure to follow this instruction may result in product damage.
- When fixing the product or coupling with a wrench, tighten under 0.15 N m. If the coupling error (parallel misalignment, angular misalignment) between the shaft
  increases while installation, the life cycle of the coupling and the encoder can be shorten.

• Do not apply tensile strength over 30 N to the cable.

### Ordering Information

This is only for reference, the actual prodcut does not support all combinations. For selecting the specified model, follow the Autonics website.



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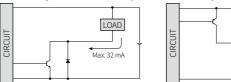
N · C: not connected
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BCD code		Binary / Gray code			
Color	Function	Refer	Color	Function	Refer
White	+V	nower	White	+V	nauvar
Black	GND	power	Black	GND	power
Brown	2 <sup>0</sup>		Brown	2 <sup>0</sup>	
Red	2 <sup>1</sup>		Red	2 <sup>1</sup>	
Orange	2 <sup>2</sup>		Orange	2 <sup>2</sup>	
Yellow	2 <sup>3</sup>		Yellow	2 <sup>3</sup>	
Blue	$2^{\circ} \times 10$		Blue	2 <sup>4</sup>	
Purple	$2^{1} \times 10$		Purple	2 <sup>5</sup>	
Gray	$2^{2} \times 10$		Gray	2 <sup>6</sup>	
White / Brown	$2^{3} \times 10$		White / Brown	2 <sup>7</sup>	
White / Red	$2^{\circ} \times 10^{2}$		White / Red	2 <sup>8</sup>	
White / Orange	$2^{1} \times 10^{2}$		White / Orange	2 <sup>9</sup>	
White / Yellow	$2^{2} \times 10^{2}$		White / Yellow	N·C	
White / Blue	$2^{3} \times 10^{2}$		White / Blue	N·C	
White / Purple	$2^{0} \times 10^{3}$		White / Purple	N·C	
Shield	F.G.	signal shield	Shield	F.G.	signal shield

# Inner Circuit

• The output circuit is identical for each output bit.





## **Output Waveform**

• Following waveform is based on the positive logic.

(In case of negative logic, the waveform is opposite to corresponding waveform.) BCD code output

2°				20 1021 102	
2 <sup>1</sup>		-	ΧХ		1
2 <sup>2</sup>	J <del>i i i</del>	1	XX		_
2 <sup>3</sup>		Ļ	XX		_
: 10 <sup>2</sup>			хx		
10 <sup>3</sup>			ХХ		-

#### Binary code output

 $2^3 \times$ 

 $2^{\circ} \times$ 

0 1 2 3	4 5 6 7 8 9	1020 1021 1022 1023
2°	Ů, Ů	X:XIIII
2 <sup>1</sup>		
2 <sup>2</sup>		X:X
2 <sup>3</sup>		x-x
:		
2 <sup>8</sup>		X:X
2°		XX

	•	•	
23 0'	0 1 2 3 4 5 6	7 8 9	1020 1021 1022 1023 (
L	2º	LL <b>I</b> XD	
l		X:	×
l	2 <sup>2</sup>		<
l	2 <sup>3</sup>		<
l	2 <sup>8</sup>	X)	ХЦЦЦ
l	2 <sup>9</sup>		x

Gray code output

## Specifications

Model	EP58	EP58		
Resolution 01)	$\leq$ 1024 division			
Output code	BCD / Binary / Gray code model			
Control output	NPN open collector output	PNP open collector output		
Inflow current	$\leq$ 32 mA	-		
Residual voltage	$\leq 1  \text{VDC}$ ==	-		
Outflow current	-	$\leq$ 32 mA		
Output voltage	-	$\geq$ (power supply - 1.5) VDC==		
Response speed <sup>02)</sup>	$T_{ON} \le 800$ nsec, $T_{OFF} \le 800$ nsec			
Max. response freq.	35 kHz			
Max. allowable revolution <sup>03)</sup>	3,000 rpm			
Approval	C€ERL			
01) Refer to resolution in 'Ou	utput Phase / Output Angle'			

02) Based on cable length: 2 m, I sink = 32 mA

03) Select resolution to satisfy Max. allowable revolution  $\geq$  Max. response revolution

[max. response frequency [max. response revolution (rpm) = resolution × 60 sec]

Shaft type	Shaft clamping type	Shaft synchro type	Hollow Built-in type	
Starting torque	$\leq$ 0.004 N m		$\leq$ 0.009 N m	
Inertia moment	$\leq 15 \mathrm{g} \cdot \mathrm{cm}^2 (1.5 \times 10^{-6} \mathrm{kg} \cdot \mathrm{m}^2)$		$\leq$ 20 g · cm <sup>2</sup> (2 × 10 <sup>-6</sup> kg · m <sup>2</sup> )	
Allowable shaft load	Radial: $\leq$ 10 kgf, Thrust: $\leq$ 2.5 kgf		Radial: $\leq$ 2 kgf, Thrust: $\leq$ 1 kgf	
Unit weight (packaged)	$\approx 435~g~(\approx 545~g)~\approx 415~g~(\approx 525~g)$		≈ 410 g (≈ 520 g)	
Power supply	5 VDC== ± 5% (ripple P-P: ≤ 5%) / 12 - 24 VDC== ± 5% (ripple P-P: ≤ 5%) model			
Current consumption	$\leq$ 100 mA (no load)			
Insulation resistance	Between all terminals and case: $\geq 100~\text{M}\Omega$ (500 VDC= megger)			
Dielectric strength	Between all terminals and case: 750 VAC $\sim 50/60$ Hz for 1 minute			
Vibration	$1 \mbox{ mm}$ double amplitude at frequency 10 to 55 Hz (for 1 minute) in each X, Y, Z direction for 2 hours			
Shock	≲ 50 G			
Ambient temp.	-10 to 70 °C, storag	ge: -25 to 85 °C (no fi	reezing or condensation)	
Ambient humi.	35 to 85%RH, storage: 35 to 90%RH (no freezing or condensation)			
Protection rating	IP50 (IEC standard)			
Connection	Axial cable type (c	able gland)		
Cable spec.	Ø 7 mm, 15-wire, 2 m, shield cable			

# · Be aware of circuit break in case of overload or short beyond the specifications.



Max. 32 mA

LOAD

#### Product Components

Shaft type	Shaft Clamping type	Shaft Synchro type	Hollow Built-in type
Product Components			Product (+ bracket), Instruction manual
Bolt	× 10	× 8	× 4
Coupling	×1	×1	-
Bracket	×1	×1	-

ring each out C: not conne	put wires.	used for output	circuit, be aware of	
BCD code			Binary / G	
or	Function	Refer	Color	

Connections	
<ul> <li>Unused wires must be insulated.</li> <li>The metal case and shield cable of encoders must be grounded</li> <li>F.G. (Frame Ground) must be grounded separately.</li> <li>Since exclusive driver IC is used for output circuit, be aware of swiring each output wires.</li> </ul>	. ,

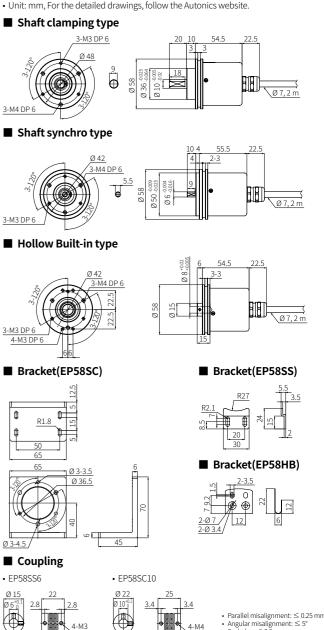
# Output Phase / Output Angle

### • TS = Signal Pulse

Resolution	BCD code	Binary code	Gray code
1024	TS: 0.3515° ±15' (13 bit)	TS: 0.3515° ±15' (10 bit)	TS: 0.703° ±15' (10 bit)
720	TS: 0.5° ±25' (11 bit)	TS: 0.5° ±25' (10 bit)	TS: 1° ±25' (10 bit)
512	TS: 0.703° ±15' (11 bit)	TS: 0.703° ±15' (9 bit)	TS: 1.406° ±15' (9 bit)
360	TS: 1° ±25' (10 bit)	TS: 1° ±25' (9 bit)	TS: 2° ±25' (9 bit)
256	TS: 1.406° ±15' (10 bit)	TS: 1.406° ±15' (8 bit)	TS: 2.8125° ±15' (8 bit)
180	TS: 2° ±25' (9 bit)	TS: 2° ±25' (8 bit)	TS: 4° ±25' (8 bit)
128	TS: 2.8125° ±15' (9 bit)	TS: 2.8125° ±15' (7 bit)	TS: 5.625° ±15' (7 bit)
90	TS: 4° ±25' (8 bit)	TS: 4° ±25' (7 bit)	TS: 8° ±25' (7 bit)
64	TS: 5.625° ±15' (7 bit)	TS: 5.625° ±15' (6 bit)	TS: 11.25° ±15' (6 bit)
45	TS: 8° ±25' (7 bit)	TS: 8° ±25' (6 bit)	TS: 16° ±25' (6 bit)

# Dimensions

• Unit: mm, For the detailed drawings, follow the Autonics website.



- Angular misalignment: ≤ 5°
   End-play: ≤ 0.5 mm

4-M4

