DIN W72×H72mm Up·Down Measure Counter

Features

- Parameter Setting
- : Input/Output operation mode, Max. counting speed, Decimal point position, OUT1/2 time (0.01 to 99.99 sec), Selectable voltage input (PNP) method or no-voltage input (NPN) method, Selectable Multiply or Divide mode function.
- Memory protection for 10 years (using non-voltage semiconductor)
- Power supply: 100-240VAC 50/60Hz
- Built-in Microprocessor



Please read "Safety Considerations" in the instruction manual before using. \mathbb{A}



M 4 M -	1P 4		
	Power supply	-4	100-240VAC 50/60Hz
		1P	1-stage setting
	Function		2-stage setting
			Indicator
Functio			Measure function
Display digit		4	9999 (4-digit)
		6	999999 (6-digit)
Size		FM	DIN W72×H72mm

Specifications

	1-	stage setting	FM4M-1P4	FM6M-1P4		
Model	2-	stage setting	FM4M-2P4	FM6M-2P4		
	In	dicator	FM4M-I4	FM6M-I4		
Display	digit		4-digit	6-digit		
Charact	ter size (W×H)	6×10mm 4×8mm			
Power s	supply		100-240VAC~ 50/60Hz	·		
Permiss	sible volt	age range	90 to 110% of rated voltage			
Power c	consump	otion	•1-stage: max. 4.6VA •2-stage: max. 5.8VA •Indicator: max. 3.8VA			
Max. cou	unting s	peed of CP1/CP2	Selectable 1cps / 30cps / 300cps / 2kcps / 5kcps			
Return t	time		Max. 500ms			
Min. sigi	nal widtl	า	RESET: approx. 20ms			
Input method			Selectable voltage input (PNP) method or no-voltage input (NPN) method [Voltage input (PNP) method]-input impedance: max. 10.8kΩ, [H]: 5-30VDC=, [L]: 0-2VDC [No-voltage input (NPN) method]-short-circuit impedance: max. 470Ω, short-circuit residual voltage: max. 1VDC, open-circuit impedance: min. 100kΩ			
One-sho	ot outpu	t time	0.01 to 99.99 sec			
	Contac	t Type	●1-stage: Instantaneous SPDT (1c) ●2-stage: Instantaneous OUT1-SPST (1a), Instantaneous OUT2-SPST (1a)			
Control		Capacity	250VAC \sim 3A, 30VDC=3A resistive load			
-	Solid	Туре	•1-stage: 1 NPN open collector •2-stage: OUT1-	1 NPN open collector, OUT2-1 NPN open collector		
	state	Capacity	NPN open collector output •Load voltage: max. 30VDC •Load current: n	nax. 100mA •Residual voltage: max 1VDC		
Relay		Mechanical	Min. 5,000,000 operations			
life cycle	е	Electrical	Min. 100,000 operations (250VAC 3A resistive load)			
Insulation resistance		ance	Over 100MΩ (at 500VDC megger)			
External power supply		supply	Max. 12VDC==±10% 50mA			
Memory retention		on	Approx. 10 years (non-volatile memory)			
Dielectri	ic streng	jth	2,000VAC 50/60Hz for 1 min (between all terminals and case)			
Noise immunity			±2kV the square wave noise (pulse width 1μs) by noise simulator			

Specifications

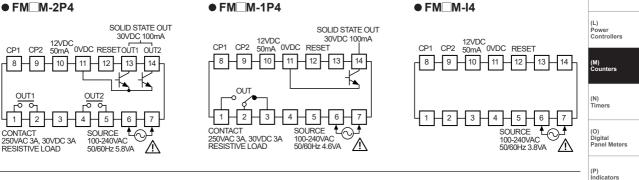
	1-stage setting	FM4M-1P4	FM6M-1P4	SENSORS	
Model	2-stage setting	FM4M-2P4	FM6M-2P4]	
	Indicator	FM4M-14	FM6M-I4		
Vibration	Mechanical	0.75mm amplitude at frequency 10 to 55Hz (for 1 mi	n) in each X, Y, Z direction for 1 hour	CONTROLLERS	
	Malfunction	0.5mm amplitude at frequency 10 to 55Hz (for 1 min) in each X, Y, Z direction for 10 min		
Shock	Mechanical	300m/s ² (approx. 30G) in each X, Y, Z direction for 3	times	MOTION DEVICES	
	Malfunction	00m/s ² (approx. 10G) in each X, Y, Z direction for 3 times			
Environ- Ambient temp.		-10 to 55°C, storage: -25 to 65°C		1	
ment	Ambient humi.	35 to 85%RH, storage: 35 to 85%RH s			
Protection s	structure	IP20 (front part, IEC standard)]	
Approval					
Weight ^{×1}	1-stage setting	Approx. 245g (approx. 180g)]	
	2-stage setting	Approx. 265g (approx. 200g)]	
	Indicator	Approx. 225g (approx. 160g)]	

%1: The weight includes packaging. The weight in parenthesis is for unit only.

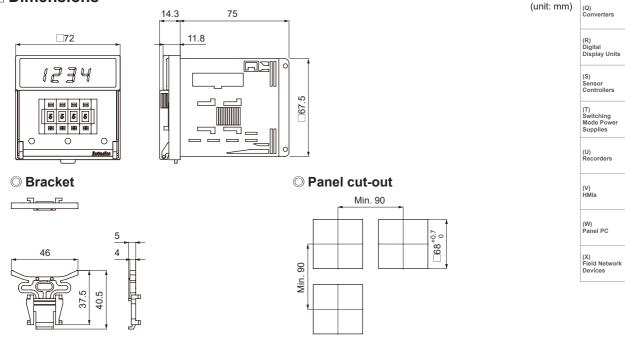
*Environment resistance is rated at no freezing or condensation.

Connections

• FM_M-2P4



Dimensions



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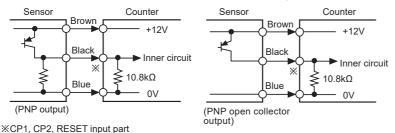
(J) Temperature Controllers

(K) SSRs

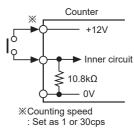
Input Connections

○ Voltage input (PNP)

• Solid-state input (standard sensor: PNP output type sensor)



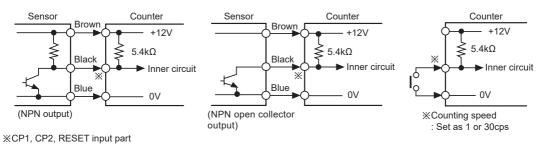
Contact input



Contact input

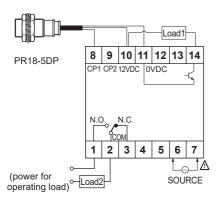
○ No-voltage input (NPN)

• Solid-state input (standard sensor: NPN output type sensor)



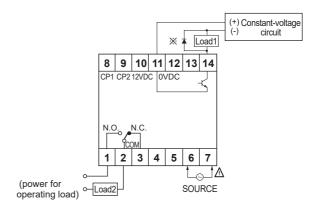
Input & Output Connections

○ When operation load by sensor power



• The sum of operating current capacity of load 1 and sensor should not be over external power capacity (50mA).

${igodot}$ When operating load by external power



- The capacity of load 1 should not be over transistor switching capacity (max. 30VDC, 100mA)
- Do not supply the reverse polarity power.
- %when using inductive load (relay, etc.), connector surge absorber at both ends of the load 1

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*Hold the MODE key for 3 sec to save the setting value and return to RUN mode after changing the setting value. SENSORS RUN mode XIf there is no key input for 60 sec while setting the parameters, the new settings are ignored, and the unit returns to RUN mode with previous settings. %Press the K, keys to select or set the desired value. Press the MODE key once after changing the setting value, MODE 3 sec MODE 3 sec to save the setting value and move to the next parameter. CONTROLLERS %The dotted line parameters may not appear depending on output specifications or other parameter settings. Input operation mode X1: Each parameter and corresponding setting value will flash alternately every 0.5 sec. Setting range: Refer to Input Operation Mode'. Ud-A n.ñ MOTION DEVICES Flashes alternately MODE SOFTWARE Output operation mode Setting range: Refer to ' Output Operation Mode'. F oUt.n 🗖 *Does not appear in indicator model. MODE Max. counting speed CP5 30 Setting range: 1, 30, 300, 22 (2,000), 52 (5,000) MODE (J) Temperature OUT2 output time Controllers oUt2 00.50 Setting range: • oUE2 (oUEE): 00.01 to 99.99 sec MODE • oUE 1: HoLd, 00.01 to 99.99 sec (K) SSRs ※In case of F, n, 5 output operation mode, oUE2 (oUEE) does not appear. OUT1 output time XIn case of 5 output operation mode for 2-stage setting, out I does not appear. ※1-stage setting model displays only out to ollt 1 🗖 Hold (L) Power Controllers MODE Decimal point position (M) Counters ※In case of multiply mode of 6-digit model, decimal point is available up to 3rd digit. dР MODE (N) Timers Input logic PnP 516 Setting range: PnP (voltage input), nPn (no-voltage input) (0) Digital Panel Meters MODE Mode setting (P) Indicators ñ-d « ≈ (Q) Converters Divide mode* Multiply mode^{*2} **NULE** dl u (R) Digital MODE MODE Display Units Divide mode Decimal point position (S) for prescale setting value Sensor Controllers Setting range 5 C.d P 0001 - - - d.5 u | : Refer to the note (%4) (T) Switching Mode Powe MODE XDisable to set it smaller than MODE Setting range · 1 to 9999 decimal point position [dP] setting. Setting value for Supplies multiply mode Setting range (U) Recorders ñ.SEL 1.000 : Refer to the note (%4). MODE ×4 (V) HMIs Memory backup Setting value Decimal Prescale decimal Setting range for multiply d A E A r E C point position point position : - EE (memory backup), mode (W) [dP] [5C.dP] [Lr (reset count value at power failure) Panel PC [ñ.5EL] MODE 0.001 to 9999 -/---.-/-Front RESET key ---. Setting range ---.-/----/-.---0.001 to 999.9 (X) Field Network r St.b : on (available front RESET key), -- ------/----0.001 to 99.99 οп Devices oFF (unavailable front RESET key) - - - -0.001 to 9.999 MODE

Parameter Setting

2: Multiply mode [FULE]: Displayed by multiplying input signal and setting value.

Input signal×Setting value=Display value (input signal: 1, setting value: 4, it displays 4(1×4))

3: Divide mode [d+u]: Displays 1 when input signals are input as the setting value. Input signal/Setting value=Display value (input signal: 4, setting value: 4, it displays 1(4/4))



Measure Counter

Measure counter sets multiply or divide integer per 1 pulse input.

Multi Mode

It multiplies the inner SW3 setting value at a count input signal and displays it.

Input signal (N)×Multi Mode preset value=Indication value

 \therefore N × 4 = 4, 8, 12 ... (N=1, 2, 3...)

• Divide Mode

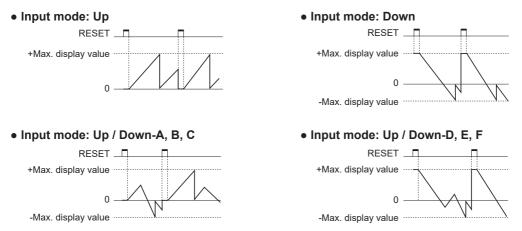
It displays as 1 when the count input signal is entered as preset value of inner SW3.

Input signal (N) Divide Mode preset value = Indication value

$$\therefore \frac{N}{5} = 1, 2, 3 \dots (N=5, 10, 15 \dots)$$

%Please be cautious the error can occur when down count is executed during up count.

Counting Operation for Indicator (FMDM-I4)



X- display is only for F, K, Q, S output operation mode and it cannot be set.

Factory Default

Parameter	Default	Parameter	Default	Parameter	Default	Parameter	Default
l n.ñ	Ud-A	oUE2	00.50	51 G	PnP	7.5 C L	1.000
oUL.ñ.	F	oUE I	Hold	ñ-d	<u>AULE</u>	d A E A	r E C
CPS	30	dР		5 C.d P		r 5£.6	on

Error Display and Output Operation

Error Display	Error description	Troubleshooting
ErrO	Setting value is 0.	Change the setting value anything but 0.

※When error occurs, the output turns OFF.

When 1st setting value is set as 0 (zero), OUT1 maintains OFF.

When 2nd setting value is smaller than 1st setting value, 1st setting value is ignored and only OUT2 output operates. %Indicator model does not have error display function.

Up·Down Measure Counter

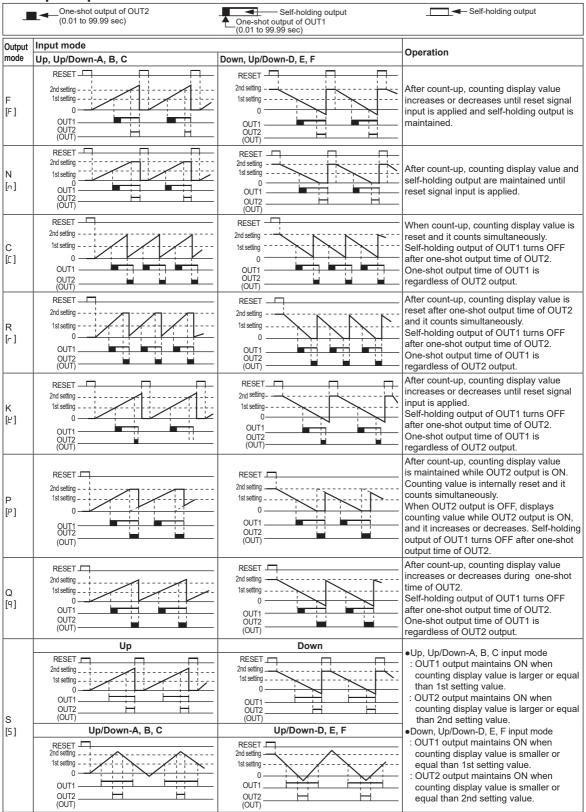
Input mode Vestage input (PMP) method Ne-voltage input (PMP) method Insuces UpDown-A (a = 1) Cost 1 Cost 2 Co	CP: Clock Pulse XCP: Clock Pulse						
UpDown-A (2 = 4) Control	Input mode	Voltage input (PNP) method	No-voltage input (PNP) method	SENSORS			
Up/Down-B individual input (Jd+b) OP1 H Court Imput Court Imput Court <thi< td=""><td>command input</td><td>$CP2 H + \frac{A}{2} + \frac{A}{2$</td><td>$CP2 H \qquad$</td><td></td></thi<>	command input	$CP2 H + \frac{A}{2} + \frac{A}{2$	$CP2 H \qquad $				
UpDown-D Individual input [Jd-f] Court 0 1 2 3 2 1 2 3 Court 0 1 2 3 4 5 Court 0 1 2 3 1 2 1 2 2 5 Court 0 1 2 3 1 2 1 2 2 5 Court 0 1 2 3 1 2 1 2 2 5 Court 0 1 2 3 1 2 1 2 2 5 Court 0 1 2 3 1 2 1 2 2 5 Court 0	individual input	$CP2 \overset{l}{\vdash} \qquad \qquad$					
$\begin{array}{c c c c c c c c c c c c c c c c c c c $	phase difference input		$CP2 \stackrel{H}{\vdash} \stackrel{BPB}{\sqcup} \stackrel{I}{\sqcup} \stackrel{I}{\iota} \stackrel{I}{\sqcup} \stackrel{I}{\iota} \stackrel{I}{\sqcup} \stackrel{I}{\iota} \stackrel{I}{\iota$	(1)			
$\begin{bmatrix} [\mu^{p}] \\ [\mu$		CP2 H $No counting$ 4 5	CP2 H CP2 H No counting Count 1 2 3 4 5	(K) SSRs			
$\begin{array}{c c c c c c c c c c c c c c c c c c c $		$CP1 H \xrightarrow{Vo counting} A$ $CP2 H \xrightarrow{A} 4$ $CP2 H \xrightarrow{A} 4$ $CP2 H \xrightarrow{A} 4$ $CP2 H \xrightarrow{A} 4$	CP2 H + A + A + A + A + A + A + A + A + A +	Controllers (M) Counters			
$\begin{array}{c c c c c c c c c c c c c c c c c c c $	command input	$CP1 \overset{H}{\sqcup} \qquad \qquad$	CP1 H CP2 H Count $n_1 n_2 n_3 n_2 n_1 n_2 n_3$	(O) Digital Panel Meters			
$\begin{array}{c c c c c c c c c c c c c c c c c c c $	individual input	$CP2 \stackrel{\text{H}}{=} \underbrace{ \begin{array}{c} & & & \\ & & & \\ & & & \\ & & & \\ Count & \stackrel{n}{=} \underbrace{ \begin{array}{c} & & \\ & & & \\ & & & \\ \end{array}} \underbrace{ \begin{array}{c} & & & \\ & & & \\ & & & \\ \end{array}} \underbrace{ \begin{array}{c} & & & \\ & & & \\ \end{array}} \underbrace{ \begin{array}{c} & & & \\ & & & \\ \end{array}} \underbrace{ \begin{array}{c} & & & \\ & & & \\ \end{array}} \underbrace{ \begin{array}{c} & & \\ & & & \\ \end{array}} \underbrace{ \begin{array}{c} & & \\ \end{array}} \underbrace{ \begin{array}{c} & & \\ & & \\ \end{array}} \underbrace{ \begin{array}{c} & & \\ & & \\ \end{array}} \underbrace{ \begin{array}{c} & & \\ & & \\ \end{array}} \underbrace{ \begin{array}{c} & & \\ \end{array}} \underbrace{ \begin{array}{c} & & \\ & & \\ \end{array}} \underbrace{ \begin{array}{c} & & \\ & & \\ \end{array}} \underbrace{ \begin{array}{c} & & \\ \end{array}} \underbrace{ \end{array}} \underbrace{ \end{array} \underbrace{ \end{array}} \underbrace{ \end{array}} \underbrace{ \end{array}} \underbrace{ \begin{array}{c} & & \\ \end{array}} \underbrace{ \end{array}} \underbrace{ \end{array} \\ \underbrace{ \end{array}} \underbrace{ \end{array}} \underbrace{ \end{array}} \underbrace{ \end{array}} \underbrace{ \end{array}} \underbrace{ \end{array}} \underbrace{ \end{array} \underbrace{ \end{array}$	CP2 L Count $\frac{n}{n-1}$ $\frac{n-2}{n-2}$ $\frac{n-1}{n-1}$ $\frac{n-2}{n-2}$ $\frac{n-3}{n-2}$	(R) Digital			
$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	phase difference input	$CP2 \stackrel{H}{\underline{H}} \stackrel{H}{\underline{H} \stackrel{H}{\underline{H}} \stackrel{H}{\underline{H}} \stackrel{H}{\underline{H}} \stackrel{H}{\underline{H}} \stackrel{H}{\underline{H}} \stackrel{H}{\underline{H} \stackrel{H}{\underline{H}} \stackrel{H}{\underline{H}} \stackrel{H}{$	$CP2 \stackrel{H}{\vdash} \stackrel{n}{\vdash} \stackrel{n}{\vdash} \stackrel{n}{\vdash} \stackrel{n}{\vdash} \stackrel{n}{\vdash} \stackrel{n}{\vdash} \stackrel{n}{\vdash} \stackrel{n}{\vdash} \stackrel{n}{\vdash} \stackrel{n}{\vdash} \stackrel{n}{\vdash} \stackrel{n}{\vdash} \stackrel{n}{\vdash} \stackrel{n}{\vdash} \stackrel{n}{\vdash} \stackrel{n}{\vdash} \stackrel{n}{\vdash}$	Sensor Controllers (T) Switching Mode Power			
$\begin{bmatrix} dn \end{bmatrix} \qquad CP1 \ \ \ \ \ \ \ \ CP1 \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \$	subtracting input	CP2 H n n $n-1$ $n-2$ $n-3$ $n-4$ $n-5$	$CP2 H \xrightarrow{n} n + \frac{A}{n} \xrightarrow{A} + \frac{A}{n}$ $CP2 H \xrightarrow{n} n + \frac{A}{n} \xrightarrow{n} A$ $(No counting)$ $Count \xrightarrow{n} n + \frac{1}{n} \xrightarrow{n} 2$ $Count \xrightarrow{n} n + \frac{1}{n} \xrightarrow{n} 5$	(V) HMIs			
		CP1 H h_{1} h_{2} h_{3} h_{4} h_{5} h_{1} h_{1} h_{2} h_{3} h_{4} h_{4} h_{5} h_{1} h_{2} h_{3} h_{4} h_{5} h_{1} h_{5} h_{1} h_{1} h_{2} h_{3} h_{4} h_{5} h_{1} h_{1} h_{1} h_{2} h_{3} h_{1} h_{1} h_{1} h_{2} h_{3} h_{1} h_{1} h_{1} h_{2} h_{1} h_{2} h_{3} h_{1} h_{1} h_{2} h_{3} h_{1} h_{1} h_{2} h_{3} h_{1} h_{1} h_{2} h_{3} h_{3} h_{3} h_{4} h_{3} h_{3	CP1 H A A A A A A A A	(X) Field Network			

Input Operation Mode

%A: over min. signal width, B: over than 1/2 of min. signal width. If the signal is smaller than these width, it may cause counting error (±1).



Output Operation Mode



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Up·Down Measure Counter

Proper Usage

 Follow instructions in 'Proper Usage'. Otherwise, it may cause unexpected accidents.
 Use the product, 0.1 sec after supplying power.
 When supplying or turning off the power, use a switch or etc. to avoid chattering.
 Install a power switch or circuit breaker in the easily accessible place for supplying or disconnecting the power.
 In case of contact input, set count speed to low speed mode (1cps or 30cps) to operate. If set to high speed mode (300cps, 2kcps, 5kcps), counting error occurs due to chattering.
 Keep away from high voltage lines or power lines to prevent inductive noise. In case installing power line and input signal line closely, use line filter or varistor at power line and shielded wire at input signal line. Do not use near the equipment which generates strong magnetic force or high frequency noise.

This product may be used in the following environments.
①Indoors (in the environment condition rated in 'Specifications')
②Altitude max. 2,000m
③Pollution degree 2
④Installation category II



(K) SSRs

Power Controllers

(L)

(M) Counters

(N) Timers

(O) Digital Panel Meters

(P) Indicators

(Q) Converters

(R) Digital Display Units

(S)

Sensor Controllers

(T) Switching Mode Power Supplies

(U) Recorders

(V) HMIs

(W) Panel PC

(X) Field Network Devices