## Dual Display PID Temperature Controllers



## TCN Series

For your safety, read and follow the considerations written in the instruction manual, other manuals and Autonics website.
The specifications, dimensions, etc are subject to change without notice for product improvement Some models may be discontinued without notice.

## Features

- Dual digital display (PV/SV)
- 100 ms high-speed sampling rate and $\pm 0.5 \%$ display accuracy
- Switch between relay output and SSR drive output (patent) *
- SSR drive output (SSRP function) control options: ON/OFF control, cycle control, phase control
- Compact design with large display panels for easier reading
- Connector plug types offer easier wiring and maintenance (TCN4S- $\square$-P)
*Korea Patent Registration 10-1002582, U.S.A. Patent Registration 8645000, Japan Patent Registration 3184816, China Patent Registration ZL200980111733.X, Vietnam Patent Registration 1-0012131, India Patent Registration 291573, Indonesia Patent Registration IDP0032166


## Safety Considerations

- Observe all 'Safety Considerations' for safe and proper operation to avoid hazards.
- $\triangle$ symbol indicates caution due to special circumstances in which hazards may occur.


## $\triangle$ Warning Failure to follow instructions may result in serious injury or death

1. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss.(e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime/disaster prevention devices, etc.)
Failure to follow this instruction may result in personal injury, economic loss or fire.
2. Do not use the unit in the place where flammable/explosive/corrosive gas, high humidity, direct sunlight, radiant heat, vibration, impact or salinity may be present.
Failure to follow this instruction may result in explosion or fire.
3. Install on a device panel to use.

Failure to follow this instruction may result in fire or electric shock.
04. Do not connect, repair, or inspect the unit while connected to a power source.
Failure to follow this instruction may result in fire or electric shock.
05. Check 'Connections' before wiring.

Failure to follow this instruction may result in fire.
06. Do not disassemble or modify the unit.

Failure to follow this instruction may result in fire or electric shock.
. Caution Failure to follow instructions may result in injury or product damage

1. When connecting the power input and relay output, use AWG $20\left(0.50 \mathrm{~mm}^{2}\right)$ cable or over, and tighten the terminal screw with a tightening torque of 0.74 to 0.90 N m .
When connecting the sensor input and communication cable without dedicated cable, use AWG 28 to 16 cable and tighten the terminal screw with a tightening torque of 0.74 to 0.90 N m .
Failure to follow this instruction may result in fire or malfunction due to contact failure.
2. Use the unit within the rated specifications.

Failure to follow this instruction may result in fire or product damage
03. Use a dry cloth to clean the unit, and do not use water or organic solvent. Failure to follow this instruction may result in fire or electric shock.
04. Keep the product away from metal chip, dust, and wire residue which flow into the unit.
Failure to follow this instruction may result in fire or product damage.

## Cautions during Use

- Follow instructions in 'Cautions during Use'. Otherwise, it may cause unexpected accidents.
- Check the polarity of the terminals before wiring the temperature sensor.
- For RTD temperature sensor, wire it as 3-wire type, using cables in same thickness and length. For thermocouple (TC) temperature sensor, use the designated compensation wire for extending wire.
- Keep away from high voltage lines or power lines to prevent inductive noise. In case installing power line and input signal line closely, use line filter or varistor at power line and shielded wire at input signal line. Do not use near the equipment which generates strong magnetic force or high frequency noise.
- Install a power switch or circuit breaker in the easily accessible place for supplying or disconnecting the power.
- Do not use the unit for other purpose (e.g. voltmeter, ammeter), but temperature controller.
- When changing the input sensor, turn off the power first before changing. After
changing the input sensor, modify the value of the corresponding parameter.
- $24 \mathrm{VAC} \sim, 24-48 \mathrm{VDC}==$ power supply should be insulated and limited voltage/current or Class 2, SELV power supply device.
- Make a required space around the unit for radiation of heat. For accurate temperature measurement, warm up the unit over 20 min after turning on the power.
- Make sure that power supply voltage reaches to the rated voltage within 2 sec after supplying power.
- Do not wire to terminals which are not used
- This unit may be used in the following environments.
- Indoors (in the environment condition rated in 'Specifications')
- Altitude Max. 2,000 m
- Pollution degree 2
- Installation category II


## Ordering Information

This is only for reference, the actual product does not support all combinations. For selecting the specified model, follow the Autonics website


## Product Components

- Product
- Instruction manual
- Bracket


## Sold Separately

- Terminal protection cover: RSA / RMA / RHA / RLA Cover


## Specifications

| Series |  | TCN4 $\square$-22 $\square$ - $\square$ | TCN4 $\square$-24 $\square$ - $\square$ |
| :---: | :---: | :---: | :---: |
| Power supply |  | $\begin{aligned} & 24 \mathrm{VAC} \sim 50 / 60 \mathrm{~Hz} \pm 10 \% \\ & 24-48 \mathrm{VDC}== \pm 10 \% \end{aligned}$ | 100-240 VAC~50/60 Hz $\pm 10 \%$ |
| Power consumption |  | $\mathrm{AC}: \leq 5 \mathrm{VA}, \mathrm{DC}: \leq 3 \mathrm{~W}$ | $\leq 5 \mathrm{VA}$ |
| Sampling period |  | 100 ms |  |
| Input specification |  | Refer to 'Input Type and Using Range. |  |
| Control output | Relay | 250 VAC $\sim 3 \mathrm{~A}, 30 \mathrm{VDC}=-=3 \mathrm{~A}$, 1a |  |
|  | SSR | $12 \mathrm{VDC}= - \pm 2 \mathrm{~V}, \leq 20 \mathrm{~mA}$ |  |
| Alarm output |  | 250 VAC $\sim 1$ A la |  |
| Display type |  | 7 Segment (red, green), LED type |  |
| Control type | Heating, Cooling | ON/OFF, P, PI, PD, PID Control |  |
| Hysteresis |  | 1 to $100(0.1 \text { to } 50.0)^{\circ} \mathrm{C} /{ }^{\circ} \mathrm{F}$ |  |
| Proportional band (P) |  | 0.1 to $999.9{ }^{\circ} \mathrm{C} /{ }^{\circ} \mathrm{F}$ |  |
| Integral time (I) |  | 0 to 9,999 sec |  |
| Derivative time (D) |  | 0 to 9,999 sec |  |
| Control cycle (T) |  | 0.5 to 120.0 sec |  |
| Manual reset |  | 0.0 to 100.0\% |  |
| Relay life cycle | Mechanical | $\geq 5,000,000$ operations |  |
|  | Electrical | OUT1/2: $\geq 200,000$ operations (load resistance: 250 VAC $\sim 3$ A) AL1/2: $\geq 300,000$ operations (load resistance: 250 VAC~ 1 A) |  |
| Dielectric strength |  | Between input terminal and power terminal: 1,000 VAC~ 50/60 Hz for 1 min | Between input terminal and power terminal: 2,000 VAC~50/60 Hz for 1 min |
| Vibration |  | 0.75 mm amplitude at frequency of 5 to 55 Hz (for 1 min ) in each $\mathrm{X}, \mathrm{Y}, \mathrm{Z}$ direction for 2 hours |  |
| Insulation resistance |  | $\geq 100 \mathrm{M} \Omega$ ( $500 \mathrm{VDC}=-=$ megger) |  |
| Noise immunity |  | $\pm 2 \mathrm{kV}$ square shaped noise (pulse width: $1 \mu \mathrm{~s}$ ) by noise simulator R-phase, S-phase |  |
| Memory retention |  | $\approx 10$ years (non-volatile semiconductor memory type) |  |
| Ambient temperature |  | -10 to $50^{\circ} \mathrm{C}$, storage: -20 to $60^{\circ} \mathrm{C}$ (no freezing or condensation) |  |
| Ambient humidity |  | 35 to 85\%RH, storage: 35 to 85\%RH (no freezing or condensation) |  |
| Insulation type |  | Mark: 回, double or reinforced insulation (dielectric strength between the measuring input part and the power part: 1 kV ) | Mark: 回, double or reinforced insulation (dielectric strength between the measuring input part and the power part: 2 kV ) |
| Approval |  | C $\epsilon_{c} \mathrm{TN}_{\mathrm{us}} \mathrm{EH}$ [ © |  |
| Unit weight (packaged) |  | -TCN4S: $\approx 100 \mathrm{~g}(\approx 147 \mathrm{~g})$ <br> -TCN4H: $\approx 124 \mathrm{~g}(\approx 194 \mathrm{~g})$ | -TCN4M: $\approx 133 \mathrm{~g}(\approx 203 \mathrm{~g})$ <br> -TCN4L: $\approx 179 \mathrm{~g}(\approx 275 \mathrm{~g})$ |

## Input Type and Using Range

| Input type |  | Decimal point | Display$\angle[R . H$ | Using range ( ${ }^{( } \mathrm{C}$ ) |  |  | Using range ( ${ }^{\circ} \mathrm{F}$ ) |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Thermo -couple | K (CA) |  |  | -50 | to | 1,200 | -58 | to 2,192 |
|  |  | 0.1 | ech.L | -50.0 | to | 999.9 | -58.0 | to 999.9 |
|  | ${ }^{\prime}$ (IC) | 1 | U $\mathrm{C} . \mathrm{H}$ | -30 | to | 800 | -22 | to 1,472 |
|  |  | 0.1 | U [.L | -30.0 | to | 800.0 | -22.0 | to 999.9 |
|  | L (IC) | 1 | L. C.H | -40 | to | 800 | -40 | to 1,472 |
|  |  | 0.1 | L L. L | -40.0 | to | 800.0 | -40.0 | to 999.9 |
|  | T (CC) | 1 | t[C.H | -50 | to | 400 | -58 | to 752 |
|  |  | 0.1 | t[C.L | -50.0 | to | 400.0 | -58.0 | to 752.0 |
|  | R (PR) | 1 | $r^{\text {Pr }}$ | 0 | to | 1,700 | 32 | to 3,092 |
|  | S(PR) | 1 | 5 Pr | 0 | to | 1,700 | 32 | to 3,092 |
| RTD | $\mathrm{Cu} 50 \Omega$ | 1 | [ 45.4 | -50 | to | 200 | -58 | to 392 |
|  |  | 0.1 | ¢ 45.1 | -50.0 | to | 200.0 | -58.0 | to 392.0 |
|  | DPt100 $\Omega$ | 1 | dPt.H | -100 | to | 400 | -148 | to 752 |
|  |  | 0.1 | dPt.L | -100.0 | to | 400.0 | -148.0 | to 752.0 |

Display accuracy

| Input type | Using temperature | Display accuracy |
| :---: | :---: | :---: |
| Thermocouple RTD | At room temperature $\left(23^{\circ} \mathrm{C} \pm 5^{\circ} \mathrm{C}\right)$ | (PV $\pm 0.5 \%$ or $\pm 1^{\circ} \mathrm{C}$ higher one) $\pm 1$-digit -Thermocouple R, S below $200^{\circ} \mathrm{C}$ : (PV $\pm 0.5 \%$ or $\pm 3^{\circ} \mathrm{C}$ higher one) $\pm 1$-digit Over $200^{\circ} \mathrm{C}$ : <br> (PV $\pm 0.5 \%$ or $\pm 2^{\circ} \mathrm{C}$ higher one) $\pm 1$ digit <br> - Thermocouple L, RTD Cu50 $\Omega$ : <br> (PV $\pm 0.5 \%$ or $\pm 2^{\circ} \mathrm{C}$ higher one) $\pm 1$-digit |
|  | Out of room temperature range | (PV $\pm 0.5 \%$ or $\pm 2^{\circ} \mathrm{C}$ higher one) $\pm 1$-digit -Thermocouple R, S below $200^{\circ} \mathrm{C}$ : (PV $\pm 1.0 \%$ or $\pm 6^{\circ} \mathrm{C}$ higher one) $\pm$ 1digit Over $200^{\circ} \mathrm{C}$ : <br> (PV $\pm 0.5 \%$ or $\pm 5^{\circ} \mathrm{C}$ higher one) $\pm 1$ digit <br> - Thermocouple L, RTD Cu50 $\Omega$ : <br> (PV $\pm 0.5 \%$ or $\pm 3^{\circ} \mathrm{C}$ higher one) $\pm$ 1digit |

- For TCN4S- $\square$-P, add $\pm 1^{\circ} \mathrm{C}$ by accuracy standard.


## Unit Descriptions <br> 

## 1. PV Display part (red)

-RUN mode: Displays PV (Present value)

- Setting mode: Displays parameter name


## 2. SV Display part (green)

- RUN mode: Displays SV (Setting value)
- Setting mode: Displays parameter setting value

| 3. Indicator |  |  |
| :--- | :--- | :--- |
| Display | Name | Description |
| AL1/2 | Alarm <br> output | Turns ON when the alarm <br> output is ON. |
| OUT | Control <br> output | Turns ON when control <br> output is ON <br> ouYCLE/PHASE control of <br> CSR drive output: Turns ON <br>  <br> when MV is over 3.0\% <br> [AC power model] |
| AT | Auto <br> tuning | Flashes during auto tuning <br> every 1 sec |
| ${ }^{\circ} \mathrm{C}, \%,{ }^{\circ} \mathrm{F}$ | Unit | Displays selected unit <br> (parameter). |


| 4. Input key |
| :--- |
| Display |
| $[$ Name |
| $[\mathbf{M O D E}]$ | Mode key $\quad$.

## Errors

| Display | Description | Troubleshooting |
| :---: | :--- | :--- |
| OPEn | Flashes when input sensor is disconnected or | Check input sensor status. |
| sensor is not connected. | HHHH | Flashes when PV is higher than input range. | | When input is within the rated input |
| :--- |
| Range, this display disappears. |

## Dimensions

- Unit: mm, For the detailed drawings, follow the Autonics website.
- Below is based on TCN4S Series .

|  |  |  |  |  |  | Panel cut-out$\stackrel{F}{\leftrightarrows}$ |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  |  |  |  | $\xrightarrow{\rightarrow}$ |
| Body |  |  |  |  |  | Panel cut-out |  |  |  |
|  | A | B | C | D | E | F | G | H | 1 |
| TCN4S | 48 | 48 | 6 | 64.5 | 44.8 | $\geq 65$ | $\geq 65$ | $45_{0}^{0.5}$ | $45^{+0.5}$ |
| TCN4S-■-P | 48 | 48 | 7.7 | 65.8 | 44.8 | $\geq 65$ | $\geq 65$ | $45_{0}^{0.5}$ | $45^{+0.5}$ |
| TCN4M | 72 | 72 | 6 | 64.5 | 67.5 | $\geq 90$ | $\geq 90$ | $68^{+0,7}$ | $68{ }_{0}^{+0,7}$ |
| TCN4H | 48 | 96 | 6 | 64.5 | 91.5 | $\geq 65$ | $\geq 115$ | $45^{+0.6}$ | $92_{0}^{10.8}$ |
| TCN4L | 96 | 96 | 6 | 64.5 | 91.5 | $\geq 115$ | $\geq 115$ | $92{ }_{0}^{10.8}$ | $92_{0}^{10.8}$ |

## Bracket

## TCN4S

Other series


## Installation Method

## TCN4S

- Other series


Insert the unit into a panel, fasten the bracket by pushing with a flathead screwdriver.

## Crimp Terminal Specifications

- Unit: mm, Use the crimp terminal of follow shape.


Wire ferrule

| Terminal <br> number | a | b | c |
| :--- | :--- | :--- | :--- |
| $\mathbf{1}$ to $\mathbf{8}$ | 6 | $\leq 1.7$ | $\leq 3.7$ |
| $\mathbf{9}$ to $\mathbf{1 1}$ | 6 to 8 | $\leq 2.1$ | $\leq 4.2$ |
| $\mathbf{1 2}$ to $\mathbf{1 4}$ | 6 to 8 | $\leq 1.5$ | $\leq 3.5$ |



Fork crimp terminal


Round crimp terminal

## Connections

- TCN4S

$\square$ TCN4S- $\square$-P


■ TCN4M


## TCN4H/L



## Mode Setting

| RUN | [MODE], [ $\mathbf{4}],[\mathbf{Q}],[\mathbf{V}] \rightarrow$ | SV setting | Move digits: [ Change value: [ $\mathbf{\Delta}],[\mathbf{\nabla}] \quad \rightarrow$ Save: [MODE] |  |
| :---: | :---: | :---: | :---: | :---: |
|  | [MODE] $2 \mathrm{sec} \rightarrow$ | Parameter 1 group | [MODE] over $3 \mathrm{sec} \rightarrow$ |  |
|  | [MODE] $4 \mathrm{sec} \rightarrow$ | Parameter 2 group | [MODE] over $3 \mathrm{sec} \rightarrow$ | RUN |
|  | $\underset{\text { sec }}{[\mathbf{4}]+[\mathbf{\Lambda}]+[\mathbf{V}] \text { over } 5} \rightarrow$ | Parameter reset | Auto $\rightarrow$ |  |
|  | $[\mathbf{\Delta}]+[\mathbf{\nabla}]$ over 3 sec $\rightarrow$ | Digital input key | Auto $\rightarrow$ |  |

## Parameter Setting

- Some parameters are activated/deactivated depending on the model or setting of other parameters. Refer to the description of each item.
- The setting range in parentheses is for using the decimal point display in the input specification.
- If there is no key input for more than 30 seconds in each parameter, it returns to RUN mode.
-When pressing the [MODE] key within 1 second after returning to the operation mode from the parameter group, it will enter the parameter group before returning. - [MODE] key: Saves the current parameter setting value and moves to the next parameter.
[【] key: Checks the fixed item / Moves the row when changing the set value
[ $\mathbf{A}],[\mathbf{\nabla}]$ keys: Selects the parameter / Changes the set value
- Recommended parameter setting sequence: Parameter 2 group $\rightarrow$ Parameter 1 group
$\rightarrow$ SV setting mode
- Parameter 1 group

| Parameter |  | Display | Default | Setting range | Condition |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 1-1 | AL1 alarm temperature | R L 1 | 1250 | Deviation alarm: -F.S. to F.S. | $\begin{aligned} & \text { 2-12/14 } \\ & \text { alarm } \end{aligned}$ |
| 1-2 | AL2 alarm temperature | RL2 | 1250 | Absolute value alarm: Within input range | operation: <br> AM1 to AM6 |
|  | Auto tuning | Rt | -FF | OFF: Stop, ON: Execution |  |
| 1-4 | Proportional band | P | 010.0 | 0.1 to $999.9{ }^{\circ} \mathrm{C} /{ }^{\circ} \mathrm{F}$ | 2-8 Control |
|  | Integral time | 1 | 0000 | 0 (OFF) to 9999 sec | typ |
| 1-6 | Derivative time | $d$ | 0000 | 0 (OFF) to 9999 sec |  |
|  | Manual reset | reSt | 050.0 | 0.0 to 100.0\% | 2-8 Control type: PID \& 1-5 Integral time: 0 |
|  | Hysteresis | H45 | 002 | 1 to $100(0.1 \text { to } 50.0)^{\circ} \mathrm{C} /{ }^{\circ} \mathrm{F}$ | 2-8 Control type: ONOF |

- Parameter 2 group

| Parameter |  | Display | Default | Setting range | Condition |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 2-1 | Input specification ${ }^{01)}$ | In-t | $\longleftarrow$ [月.H | Refer to 'Input Type and Using Range'. | - |
| 2-2 | Temperature unit ${ }^{\text {11) }}$ | Unit | - [ | ${ }^{\circ} \mathrm{C},{ }^{\circ} \mathrm{F}$ | - |
| 2-3 | Input correction | $1 \mathrm{n}-\mathrm{b}$ | 0000 | -999 to 999 (-199.9 to 999.9) ${ }^{\circ} \mathrm{C} /{ }^{\circ} \mathrm{F}$ | - |
| 2-4 | Input digital filter | -̇Ru.F | 000.1 | 0.1 to 120.0 sec | - |
| 2-5 | SV low limit ${ }^{(2)}$ | L-5u | -50 | Within 2-1 Input specification Input | - |
|  | SV high limit ${ }^{\text {22) }}$ | H-5u | 1200 | $\begin{aligned} & \text { L-SV } \leq \mathrm{H} \text {-SV - } 1 \text {-digit }{ }^{\circ} \mathrm{C} /{ }^{\circ} \mathrm{F} \\ & \mathrm{H}-\mathrm{SV} \geq \mathrm{L} \text {-SV }+1 \text {-digit }{ }^{\circ} \mathrm{C} /{ }^{\circ} \mathrm{F} \end{aligned}$ |  |
| 2-7 | Control output mode ${ }^{031}$ | O-Ft | HEAt | HEAT: Heating, COOL: Cooling | - |
|  | Control type ${ }^{(4)}$ | [-nd | Pid | PID, ONOF: ON/OFF |  |
| 2-9 | Control output | -ut | rly | RLY: relay, SSR |  |
| 2-10 | SSR drive output type | 55 r.n̄ | 5tnd | [AC model] STND: standard, CYCL: cycle, PHAS: phase | 2-9 Control output: SSR |
| 2-11 Control cycle |  | t | 20.0 | 0.5 to 120.0 sec | 2-9 Control output: RLY 2-10 SSR drive output type: STND |
|  |  | 2.0 | 2-9 Control output: SSR 2-10 SSR drive output type: STND |  |
|  | AL1 alarm operation |  | AL- 1 |  | AM0: Off <br> AM1: Deviation high limit alarm AM2: Deviation low limit alarm AM3: Deviation high, low limit alarm AM4: Deviation high, low reverse alarm AM5: Absolute value high limit alarm AM6: Absolute value low limit alarm SBA: Sensor break alarm LBA: Loop break alarm (LBA) |  |
|  | AL1 alarm option | A: Standard B: Alarm latch <br> alarm D: Alarm latch and <br> C: Standby standby sequence 1 <br> sequence 1 F: Alarm latch and <br> E: Standby standby sequence 2 <br> sequence 2 stan <br> - Enter to option setting: Press [ [4] key  <br> in 2-12 AL-1 alarm operation.  |  |  |  |
|  | AL2 alarm operation | AL-2 | Añ. A | Same as 2-12/13 AL1 alarm operation/ option |  |
|  | AL2 alarm option |  |  |  |  |
| 2-16 | Alarm output hysteresis | RHY5 | 001 | 1 to $100(0.1 \text { to } 50.0)^{\circ} \mathrm{C} /{ }^{\circ} \mathrm{F}$ | $\begin{aligned} & \text { 2-12/14 } \\ & \text { AL1/2 alarm } \\ & \text { operation: } \\ & \text { AM1 to } 6 \end{aligned}$ |
| 2-17 | LBA time | LbA.t | 0000 | 0 (OFF) to 9999 sec or auto (auto tunning) | 2-12/14 <br> AL1/2 alarm operation: LBA |
| 2-18 | LBA band | L6\%.b | 0002 | 0 (OFF) to $999(0.0 \text { to } 999.9)^{\circ} \mathrm{C} /{ }^{\circ} \mathrm{F}$ or auto (auto tunning) | 2-12/14 <br> AL1/2 alarm <br> operation: <br> LBA \& 2-18 <br> LBA time: > 0 |
| 2-19 | Digital input key | di-u | 5top | STOP: Stop control output, AL.RE: Alarm reset, AT*: Auto tuning execution, OFF | *2-8Control type: PID |
| 2-20 | Sensor error MV | Er.ñu | 000.0 | 0.0: OFF, 100.0: ON | 2-8 Control type: ONOF |
|  |  |  |  | 0.0 to 100.0\% | 2-8 Control type: PID |
| 2-21 | Lock | LoL | oFF | OFF <br> LOC1: Parameter 2 group lock <br> LOC2: Parameter $1 / 2$ group lock <br> LOC3: Parameter 1/2 group, SV setting lock | - |

1) Below parameters are initialized when the setting value is changed.

Parameter 1 group: AL1/2 alarm temperature
Parameter 2 group: Input correction, SV high/low limit, Alarm output hysteresis, LBA time, LBA band SV setting mode: SV
02) If SV is lower than low limit or higher than high limit when the value is changed, SV is changed to the low/high mit value.
$\mathrm{f} 2-1$ Input specification is changed, the value is changed to Min./Max. value of Input specification.
$03)$ When the setting value is changed, setting value of $2-20$ Sensor error MV is initialized to 0.0 (OFF).
04) When changing the value from PID to ONOF, each value of following parameter is changed.

## Function: Alarm

■ II. - I Set both alarm operation and alarm option by combining, Alarm Alarm Each alarm operates individually in two alarm output models operation option When the current temperature is out of alarm range, alarm clears automatically.

Operation

- H: Alarm output hysteresis

| Name | Alarm operation |  | Description |
| :---: | :---: | :---: | :---: |
| - | - Ala |  | No alarm output |
| Deviation high limit | OFF ${ }^{\text {H4 }}$ | OFF ${ }^{\text {H7 }}$ ON | If deviation between PV and SV as high-limit is higher than set value of deviation temperature, the alarm output will be ON. |
|  | $\begin{array}{cc} \Delta \mathrm{SV} & \Delta \\ 100^{\circ} \mathrm{C} & 110^{\circ} \mathrm{C} \\ \hline \end{array}$ |  |  |
|  | High deviation: Set as $10^{\circ} \mathrm{C}$ | High deviation: Set as $-10^{\circ} \mathrm{C}$ |  |
| Deviation low limit | ON ${ }^{\text {H/ }}$ | ON 4 H, OFF | If deviation between PV and SV as low limit is higher than set value of deviation temperature, the alarm output will be ON. |
|  |  | $\begin{array}{cc}\Delta \mathrm{SV} & \triangle \\ \mathrm{PV} \\ 100^{\circ} \mathrm{C} & 110^{\circ} \mathrm{C}\end{array}$ |  |
|  | Low deviation: Set as $10^{\circ} \mathrm{C}$ | Low deviation: Set as $-10^{\circ} \mathrm{C}$ |  |
| Deviation high, low limit | ON ${ }^{-} \mathrm{H}$ OFF $\mathrm{H}^{2}$ ON |  | If deviation between PV and SV as high/low-limit is higher than set value of deviation temperature, the alarm output will be ON. |
|  | $\begin{gathered} \Delta v \\ \hline P V \\ 90^{\circ} \mathrm{C} \end{gathered}$ | $\begin{gathered} \Delta \\ \stackrel{\rightharpoonup}{P V} \\ 110^{\circ} \mathrm{C} \end{gathered}$ |  |
|  | High, Low deviation: Set as $10^{\circ} \mathrm{C}$ |  |  |
| Deviation high, low limit reverse | OFF ${ }^{\text {H }}$ | ON $\quad$ - $\mathrm{H} \downarrow$ OFF | If deviation between PV and |
|  | $\begin{array}{ll} \hline \mathrm{PV} \\ 90^{\circ} \mathrm{C} & 10 \end{array}$ | $\begin{array}{cc}  & \mathrm{PV} \\ & 110^{\circ} \mathrm{C} \\ \hline{ }^{\circ} \mathrm{C} & \end{array}$ | SV as high/low-limit is lower than set value of deviation |
|  | High, Low deviation: Set as $10^{\circ} \mathrm{C}$ |  | output will be OFF. |
| Absolute value high limit | OFF $\mathrm{V}^{4} \mathrm{ON}$ | OFF $\quad \mathrm{H}^{4} \mathrm{ON}$ | If PV is higher than the absolute value, the output will be ON. |
|  | $\Delta \mathrm{PV}$ $90^{\circ} \mathrm{C}$ $\begin{gathered}\mathrm{SV} \\ 100^{\circ} \mathrm{C}\end{gathered}$ | $\begin{array}{cc} \hline \mathrm{SV} & \stackrel{\rightharpoonup}{\mathrm{P}} \\ 100^{\circ} \mathrm{C} & 110^{\circ} \mathrm{C} \\ \hline \end{array}$ |  |
|  | Absolute value: Set as $90^{\circ} \mathrm{C}$ | Absolute value: Set as $110^{\circ} \mathrm{C}$ |  |
| Absolute value low limit | ON ${ }^{4} \mathrm{H}$ | ON $\uparrow+\mathrm{H}_{\square} \mathrm{OFF}$ | If $P V$ is lower than the absolute value, the output will be ON. |
|  | $\begin{array}{cc} \Delta \mathrm{PV} & \underset{\mathrm{SV}}{\mathrm{PV}} \\ 90^{\circ} \mathrm{C} & 100^{\circ} \mathrm{C} \\ \hline \end{array}$ | $\begin{array}{\|cc\|} \hline \mathbf{S V} & \triangle \\ \mathrm{PV} \\ 100^{\circ} \mathrm{C} & 110^{\circ} \mathrm{C} \\ \hline \end{array}$ |  |
|  | Absolute value: Setas $90^{\circ} \mathrm{C}$ | Absolute value: Set as $110^{\circ} \mathrm{C}$ |  |
| Sensor break | - |  | It will be ON when it detects sensor disconnection. |
| Loop break | - |  | It will be ON when it detects loop disconnection. |


| Option |  | Condition <br> of re-apply |
| :--- | :--- | :--- |
| Name | Description | - |
| Standard <br> alarm | If it is an alarm condition, alarm output is ON. If it is a clear alarm <br> condition, alarm output is OFF. | - |
| Alarm latch | If it is an alarm condition, alarm output is ON and maintains ON <br> status. | First alarm condition is ignored and from second alarm <br> condition, standard alarm operates. When power is supplied <br> and it is an alarm condition, this first alarm condition is ignored <br> and from the second alarm condition, standard alarm operates. |

## Segment Table

The segments displayed on the product indicate the following meanings．It may differ depending on the product．

| 7 segment |  |  |  | 11 segment |  |  |  | 12 segment |  |  |  | 16 segment |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | i | 1 | 0 | 0 | 1 | I | 0 | 0 | 1 | I | 0 | 0 | I | 1 |
| 1 | 1 | U | J | 1 | 1 | U | J | 1 | 1 | ل | J | 1 | 1 | J | J |
| 2 | 2 | $匕$ | K | 2 | 2 | ＇ | K | 2 | 2 | K | K | 2 | 2 | k | K |
| 3 | 3 | L | L | 3 | 3 | L | L | 3 | 3 | L | L | 3 | 3 | L | L |
| 4 | 4 | ก̄ | M | 4 | 4 | M | M | 4 | 4 | M | M | 4 | 4 | M | M |
| 5 | 5 | ก | N | 5 | 5 | N | N | 5 | 5 | N | N | 5 | 5 | id | N |
| 5 | 6 | 0 | 0 | 5 | 6 | $\bigcirc$ | 0 | 5 | 6 | 0 | 0 | 5 | 6 | 2 | 0 |
| 7 | 7 | $P$ | P | 7 | 7 | P | P | 7 | 7 | $\rho$ | P | 7 | 7 | P | P |
| 8 | 8 | 9 | Q | 8 | 8 | 3 | Q | 8 | 8 | 0 | Q | 8 | 8 | 0 | Q |
| 9 | 9 | r | R | 9 | 9 | R | R | 9 | 9 | 只 | R | 9 | 9 | P | R |
| A | A | 5 | S | A | A | 5 | S | A | A | 5 | S | A | A | 5 | S |
| $b$ | B | t | T | $b$ | B | t | T | b | B | $t$ | T | 3 | B | T | T |
| ［ | C | $U$ | U | ［ | C | $U$ | U | ［ | C | $U$ | U | ［ | C | $\square$ | U |
| d | D | $\cup$ | V | d | D | ＂ | V | $d$ | D | ！ | V | 3 | D | ！ | V |
| E | E | $\because$ | W | E | E | in | W | E | E | W | W | E | E | 4 | W |
| $F$ | F | 4 | X | $F$ | F | $\check{ }$ | X | $F$ | F | $\cdots$ | X | $F$ | F | ＊ | X |
| ［ | G | 4 | Y | ［ | G | $y$ | Y | 5 | G | 4 | Y | 5 | G | i | Y |
| H | H | 三 | Z | H | H | 7 | Z | H | H | 7 | Z | H | H | Z | Z |

