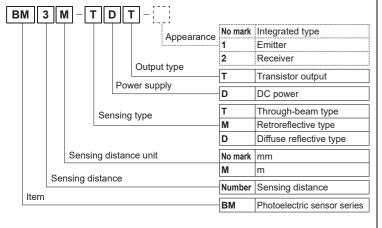
Autonics Photoelectric Sensor **BM SERIES** INSTRUCTION MANUAL CE Thank you for choosing our Autonics product. Please read the following safety considerations before use. Safety Considerations ×Please observe all safety considerations for safe and proper product operation to avoid hazards $imes \Delta$ symbol represents caution due to special circumstances in which hazards may occur. **Warning** Failure to follow these instructions may result in serious injury or death. **Caution** Failure to follow these instructions may result in personal injury or product damage. **∆** Warning 1. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss. (e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime/disaster prevention devices, etc.) Failure to follow this instruction may result in personal injury, economic loss or fire. 2. Do not use the unit in the place where flammable/explosive/corrosive gas, high humidity, direct sunlight, radiant heat, vibration, impact, or salinity may be present. Failure to follow this instruction may result in explosion or fire. 3. Do not disassemble or modify the unit. Failure to follow this instruction may result in fire 4. Do not connect, repair, or inspect the unit while connected to a power source. Failure to follow this instruction may result in fire 5. Check 'Connections' before wiring. Failure to follow this instruction may result in fire **∆**Caution 1. Use the unit within the rated specifications. Failure to follow this instruction may result in fire or product damage. 2. Use a dry cloth to clean the unit, and do not use water or organic solvent. Failure to follow this instruction may result in fire.

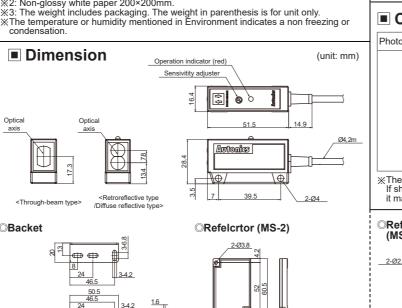
Ordering Information



%The above specifications are subject to change and some models may be discontinued without notice. *Be sure to follow cautions written in the instruction manual and the technical

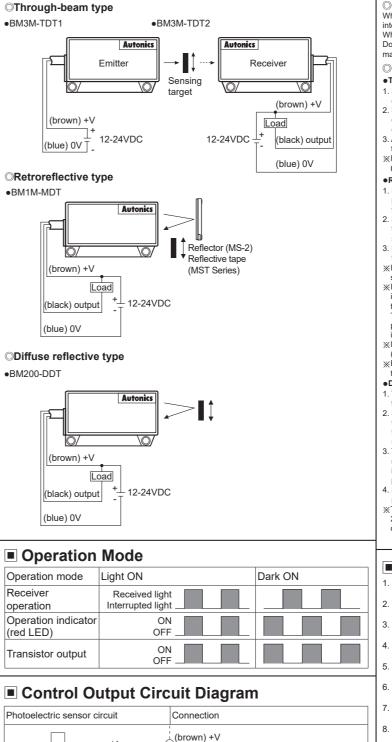
descriptions (catalog, homepage

Model		BM3M-TDT	BM1M-MDT	BM200-DDT	
Sensing type		Through-beam	Retroreflective	Diffuse reflective	
Sensing distance		3m	1m ^{**1}	200mm ^{**2}	
Sensing target		Opaque materials over Ø8mm	Opaque materials of over Ø60mm	Transparent, translucent, opaque materials	
Hysteresis		_		Max. 10% at sensing distance	
Response time		Max. 3ms			
Power supply		12-24VDC ±10% (ripple P-P: max. 10%)			
Current consumption		Max. 45mA Max. 40mA			
Light source		Infrared LED (940nm)			
Sensitivity adjustment		Fixed		Sensitivity adjuster	
Operation mode		Dark ON		Light ON (Dark ON: option)	
Control output		NPN open collector output Load voltage: max. 30VDC=, load current: max. 100mA, residual voltage: max. 1VDC=			
Protection circuit		Power reverse polarity protection circuit			
Indication		Operation indicator: red LED			
Connection		Cable type			
Insulation resistance					
Noise immunity		$\pm 240V$ the square wave noise (pulse width:1 $\mu s)$ by the noise simulator			
Dielectric strength		1,000VAC 50/60Hz for 1 minute			
Vibration		1.5mm amplitude at frequency of 10 to 55Hz in each X, Y, Z direction for 2 hours			
Shock		500m/s ² (approx. 50G) in each X, Y, Z direction for 3 times			
	Ambient illumination	Sunlight: max. 11,000lx, incandescent lamp: max. 3,000lx (receiver illumination)			
Environ ment	Ambient temperature	-10 to 60°C, storage : -25 to 70°C			
	Ambient humidity	35 to 85%RH, storage : 35 to 85%RH			
Material		Case: acrylonitrile butadiene styrene, sensing part: polycarbonate, bracket: steel plate cold commercial, bolt, nut: steel chromium molybdenum	Case: acrylonitrile butadiene styrene, sensing part: acrylic, bracket: steel plate cold commercial, bolt, nut: steel chromium molybdenum		
Cable		Ø4mm, 3-wire, 2m (emitter of through-beam type: Ø4mm, 2-wire, 2m) (AWG22, core diameter: 0.08mm, number of cores: 60, insulator out diameter: Ø1.25mm)			
Acces	Individual		Reflector (MS-2)	Adjuster driver	
sories	Common	Fixing bracket, M4 bolt: 4, M4 nut: 4	Fixing bracket, M4 bolt: 2, M4 nut: 2		
Approval		CE			
Weight ^{**3}		Approx. 240g (approx. 170g)	Approx. 188g (approx. 105g)	Approx. 156g (approx. 88g)	
whe The usir the %2: Nor %3: The	en using MS-5 distance bet ag reflective ta catalog or we a-glossy white weight include	ance is specified with 5 (sold separately). ween the sensor and i apes, the reflectivity w b site. paper 200×200mm. des packaging. The w humidity mentioned i	the reflector should be ill vary by size of the t eight in parenthesis is	e set over 0.1m. Wher ape. Please refer to for unit only.	

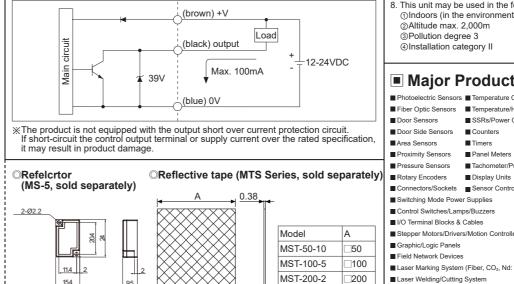


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⊡ ⊕



Connection



Installation and Adjustment

○ For installation

When using photoelectric sensors closely over two units, it may result in malfunction due to mutual interference

When installing the product, tighten the screw with a tightening torque of 0.8 N.m. Do not impact on the unit with the hard object or bend the cable with excessive power. Otherwise, It may result in damage to the waterproof function.

For optical axis adjustment

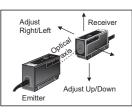
•Through-beam type

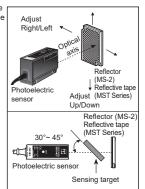
. Supply the power to the photoelectric sensor, after setting the emitter and the receiver facing each other. 2. Set the receiver in center of position in the middle of the

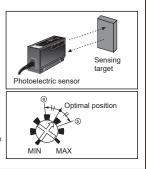
- operation range of indicator by adjusting the receiver or the emitter right and left, up and down.
- After the adjustment, check the stability of operation by putting the object at the optical axis.
- ×If the sensing target is translucent body or smaller than
- Ø8mm, it can be missed by sensor because light penetrate it Retroreflective type
- Supply the power to the photoelectric sensor, after setting the photoelectric sensor and the reflector (MS-2) or reflective tape
- face to face 2. Set the photoelectric sensor in the position which indicator
- turns on, by adjusting the reflector, reflective tape or the sensor right and left, up and down.
- . Fix both units tightly after checking that the unit detects the target.
- % If using more than 2 photoelectric sensors in parallel, the
- space between each of them should be more than 30cm. %If reflectance of target is higher than non-glossy white paper, it might cause malfunction by reflection from the target when the target is near to photoelectric sensor.
- Therefore put enough space between the target and the photoelectric sensor or the surface of the target should be installed at angle of 30° to 45° against optical axis.
- %If the mounting place is too narrow, please use the reflector (MS-5) instead of the reflector (MS-2).
- »Please use reflective tape (MST series) for the place where the reflector cannot be installed.

Diffuse reflective type

- . The sensitivity should be adjusted depending on a sensing target or mounting place.
- 2. Set the target at a position to be detected by the beam, then turn the sensitivity adjuster until position (a) where the operation indicator turns ON from MIN position of the sensitivity adjuster.
- 5. Take the target out of the sensing area, then turn the sensitivity adjuster until position (6) where the operation indicator turns ON. If the indicator dose not turn ON, MAX position is (b)
- Set the sensitivity adjuster at the center of two switching position @, 6.
- The sensing distance indicated on specification chart is for 200×200mm of non-glossy white paper. Be sure that it can be different by size, surface and gloss of target.







Cautions during Use

- . Follow instructions in 'Cautions during Use'. Otherwise, It may cause unexpected accidents
- . When connecting a DC relay or other inductive load to the output, remove surge by using diodes or varistors. 3. Use the product, 0.5 sec after supplying power.
- When using separate power supply for the sensor and load, supply power to sensor first. Power supply should be insulated and limited voltage/current or Class 2, SELV power supply device
- . Wire as short as possible and keep away from high voltage lines or power lines, to prevent inductive noise
- 6. When using switching mode power supply to supply the power, ground F.G. terminal and connect a condenser between 0V and F.G. terminal to remove noise
- . When using sensor with the equipment which generates noise (switching regulator inverter, servo motor, etc.), ground F.G. terminal of the equipment
- 3. This unit may be used in the following environments.
- (Indoors (in the environment condition rated in 'Specifications')
- ②Altitude max. 2,000m
- ③Pollution degree 3
- ④Installation category I

Major Products

- Fiber Optic Sensors Temperature/Humidity Transducers
- Door Sensors SSRs/Power Controllers
- Door Side Sensors Counters
- Area Sensors
- Proximity Sensors
- Pressure Sensors Tachometer/Pulse (Rate) Meters
- Panel Meters
- Connectors/Sockets Sensor Controllers
- Switching Mode Power Supplies
- Control Switches/Lamps/Buzzers
- I/O Terminal Blocks & Cables
- Stepper Motors/Drivers/Motion Controllers
- Graphic/Logic Panels
- Field Network Devices
- Laser Marking System (Fiber, CO₂, Nd; YAG)
- Laser Welding/Cutting System

Autonics Corporation http://www.autonics.com

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- E-mail: sales@autonics.

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- Photoelectric Sensors Temperature Controllers

 - Timers