

Inherently safe, truly collaborative. You and me.

YuMi is the first truly collaborative dual-armed robot, designed for a world in which humans and robots work together. It heralds a new era of robotic coworkers which are able to work side-by-side on the same tasks as humans with extreme accuracy while ensuring the safety of those around it.



Collaboration

YuMi is designed to meet the flexible and agile production needs required for small parts assembly in the electronics industry. It is also well suited to other small parts environments, including the manufacture of watches, toys and automotive components. All of this thanks to its dual-arms, flexible hands, universal parts feeding system, camera-based part location and stateof-the-art motion control.

Redefining safety

YuMi has a lightweight yet rigid magnesium skeleton covered with a floating plastic casing wrapped in soft padding, which absorbs the force of any unexpected impacts to a very high degree. YuMi has no pinch points so that sensitive ancillary parts cannot be crushed between two opposing surfaces as the axes open and close.

If YuMi senses an unexpected impact or change in its environment such as a collision with a coworker, it can pause its motion within milliseconds to prevent injury, and the motion can be restarted again as easily as pressing play on a remote control.

YuMi is very precise and fast, returning to the same point in space over and over again to within 0.02 mm accuracy and moving at a maximum velocity of 1,500 mm/sec. This ensures the safety of human coworkers on production lines and in fabricating cells.

Total solution concept

ABB also develops software and manufactures hardware, peripheral equipment, process equipment and modular manufacturing cells. This "total solution" concept is evident in YuMi's breakthrough design.

Features

- The fifth-generation, integrated IRC5 controller with TrueMove and QuickMove[™] motion control technology commands accuracy, speed, cycle-time, programmability and synchronization with external devices.
- I/O interfaces include Ethernet IP, Profibus, USB ports, DeviceNet[™], communication port, emergency stop and air-to-hands. YuMi accepts a wide range of HMI devices including ABB's teach pendant, industrial displays and commercially available tablets.
- The 100-240 volt power supply plugs into any power socket for worldwide versatility.

Benefits

- Can operate equally effectively side-by-side or face-toface with human coworkers.
- Servo grippers (the "hands") include options for built-in cameras.
- Real-time algorithms set a collision-free path for each arm customized for the required task.
- Padding protects coworkers in high-risk areas by absorbing force if contact is made.

Specification

Robot version	Reach (mm)	Payload (g)	Armload
IRB 14000-0.5/0.5	559	500	No armloads
Number of axes	14		
Protection	Std: IP30 and Clean Room		
Mounting	Table		
Controller	Integrated IRC5		
Customer power supply	24V/1A supply		
Customer signals	4 signals (for IO, Fieldbus, or Ethernet)		
Integrated air supply	1 per Arm on tool Flange (4 Bar)		
Functional safety	SafeMove Collaborative included All safety functions certified to Category B, PL b		

Performance (according to ISO 9283)

Max TCP Velocity	1.5 m/s
Max TCP Acceleration (normal control motion @nominal load)	39.1 m/s²
Max TCP Acceleration (e-stop @nominal load)	85.4 m/s²
Acceleration time 0–1m/s	0.12 s
Pose repeatability	0.02 mm
0.5 kg picking cycle 25 × 300 × 25 mm	0.86 s

Physical

J =	
Robot base	399 × 496 mm
Robot toes	399 × 134 mm
Weight	38 kg

Movement

Axis movement	Working range	Axis max. speed
Axis 1 rotation	-168.5° to +168.5°	180°/s
Axis 2 arm bend	-143.5° to +43.5°	180°/s
Axis 7 arm rotation	-168.5° to +168.5°	180°/s
Axis 3 arm bend	-123.5° to +80°	180°/s
Axis 4 wrist rotation	-290° to +290°	400°/s
Axis 5 wrist bend	-88° to +138°	400°/s
Axis 6 flange rotation	-229° to +229°	400°/s

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Top view



Front view





Inherently safe, truly collaborative. You and me.

Best-in-class safety. Ultimate flexibility. Approachable design. YuMi was engineered to work directly alongside your people, and boost productivity.

Following on from the success of ABB's dual-arm YuMi, introduced in 2015, the world's first truly collaborative robot, ABB has developed a single-arm YuMi to expand its collaborative portfolio.

Versatile installation for convenient deployment

Single-arm YuMi is compact and lightweight (9.5 kg) and supports mounting in any direction including ceiling, table, and wall mounting for rapid and flexible installation to fit into existing production lines. The ultra-light magnesium arm rotates on seven axes to mimic humanlike movements with greater agility than 6-axis robots. The robot was specifically designed to meet the flexible production needs required by small parts assembly processes including consumer electronics, consumer goods, and small and medium enterprises.

Easy-to-use lead-through programming

Single-arm YuMi also features the same intuitive, easyto-use lead-through movement programming as dualarm YuMi, meaning workers can teach the robot motions and positions easily and quickly, greatly simplifying robot programming. Combining this simplicity with the robot's deployment flexibility, it will help manufacturers in many industries to offset shortages of skilled workers and help reduce entry barriers for new potential robot users, particularly small and medium enterprises. Extremely versatile, the YuMi family of robots can be combined in numerous configurations. For example, a single-arm YuMi can be used to feed parts to dual-arm YuMi to increase flexibility, or added as an extra arm for more complex assembly tasks requiring more than 2 robot arms.



Wizard easy programming

Single-arm YuMi comes delivered with Wizard, ABB's new graphical programming interface that enables you to quickly create robot programs using drag-and-drop blocks on the Flexpendant.

SaveMove option

To fulfill the enhanced safety requirements of specific usage scenarios, ABB's SafeMove will be available as option for the single-arm YuMi, giving it the full range of safety certified functions that other ABB robots have.

Key features

- 500 g rated payload
- Small footprint, 7-axis dexterity
- Very lightweight manipulator, 9.5 kg
- Mounting in any position
- Integrated gripper with servo gripper, vision and vacuum
- Best-in-class safety design
- High speed and accuracy
- PL d Cat 3 Protective stop and emergency stop

Customer benefits

- Short cycle times
- Fenceless operation
- Lead-through technology
- Wizard easy programming
- Lower investment
- Easier to integrate

Specification

Robot version	Reach (mm)	Payload (g)	Armload
IRB 14050	559	500	No armloads
Number of axes	7		
Protection	Std: IP30 and Clean Room		
Mounting	All angles. AbsAcc available for all mounting positions.		
Controller	OmniCore C30		
Customer power supply	24V/1A supply		
Customer signals	4 signals (for IO, Fieldbus, or Ethernet)		
Integrated air supply	4 Bar		
Functional safety	PL d Cat 3 and emer SafeMove	B Protective gency stop as option	stop

Performance (according to ISO 9283)

Max TCP Velocity	1.5 m/s
Max TCP Acceleration (normal control motion @nominal load)	39.1 m/s²
Max TCP Acceleration (e-stop @nominal load)	85.4 m/s²
Acceleration time 0-1m/s	0.12 s
Pose repeatability	0.02 mm
0.5 kg picking cycle 25 × 300 × 25 mm	0.86 s

160 × 160 mm

9.5 kg

Physical

Dimensions bottom Weight

Movement

Axis movement	Working range	Axis max. speed
Axis 1 rotation	-168.5° to 168.5°	180°/s
Axis 2 arm	-143.5° to 43.5°	180°/s
Axis 3 arm	-123.5° to 80.0°	180°/s
Axis 4 wrist	-290.0° to 290.0°	400°/s
Axis 5 bend	-88.0° to 138.0°	400°/s
Axis 6 turn	-229.0° to 229.0°	400°/s
Axis 7 rotation	-168.5° to 168.5°	180°/s





Front view



Front view



Front view



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