# Standard / Built-in Brake Type 5-phase Stepper Motor $(\Box 24 \text{ mm}, \Box 42 \text{ mm}, \Box 60 \text{ mm}, \Box 85 \text{ mm})$

# **AK Series** INSTRUCTION MANUAL

TCD210122AA

**Autonics** 

Thank you for choosing our Autonics product.

Read and understand the instruction manual and manual thoroughly before using the product.

For your safety, read and follow the below safety considerations before using. For your safety, read and follow the considerations written in the instruction manual, other manuals and Autonics website.

Keep this instruction manual in a place where you can find easily.

The specifications, dimensions, etc. are subject to change without notice for product improvement. Some models may be discontinued without notice. Follow Autonics website for the latest information.

## Safety Considerations

- · Observe all 'Safety Considerations' for safe and proper operation to avoid hazards.
- $\Lambda$  symbol indicates caution due to special circumstances in which hazards may occur.

**Warning** Failure to follow instructions may result in serious injury or death.

- 01. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss. (e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime / disaster prevention devices, etc.)
- Failure to follow this instruction may result in personal injury, economic loss or fire. 02. Do not use the unit in the place where flammable / explosive / corrosive gas, high humidity, direct sunlight, radiant heat, vibration, impact or salinity may be present. ilure to follow this instruction may result in explosion or fire.
- 03. Do not use the brake for safety. Failure to follow this instruction may result in personal injury or product and ambient ouinment damage

04. Fix the unit on the metal plate.

- Failure to follow this instruction may result in personal injury or product and ambient equipment damage
- 05. Do not connect, repair, or inspect the unit while connected to a power source. re to follow this instruction may result in fire 06. Install the unit after considering counter plan against power failure.
- ailure to follow this instruction may result in personal injury, economic loss or fire 07. Check 'Connections' before wiring.
- ure to follow this instruction m result in fire
- 08. Do not disassemble or modify the unit. re to follow this instruction may result in fire or electric shock.
- 09. Install the motor in the housing or ground it.
- ailure to follow this instruction may result in personal injury. fire or electronic shock. 10. Make sure to install covers on motor rotating components.
- ilure to follow this instruction may result in personal ir 11. Do not touch the unit during or after operation for a while.
- lure to follow this instruction may result in burn due to high temperature of the surface. 12. Upon occurrence of an error, disconnect the power source. Failure to follow this instruction may result in personal injury, fire or electronic shock.

### **Caution** Failure to follow instructions may result in injury or product damage.

01. Use the unit within the rated specifications.

- ailure to follow this instruction may result in fire or product damage 02. Use a dry cloth to clean the unit, and do not use water or organic solvent. re to follow this instruction nay result in fire
- 03. The motor may overheat depending on the environment Install the unit at the well-ventilated environment and forced cooling with a cooling fan.
- re to follow this instruction may result in product damage or degra 04. Keep the product away from metal chip, dust, and wire residue which flow into the unit. ailure to follow this instruction may result in fire or product damage

# **Cautions during Use**

- Follow instructions in 'Cautions during Use'.
- Otherwise, it may cause unexpected accidents • At low temperature, reducing the grease's consistency of ball-baring and etc. causes the friction torque increment.
- Start the motor gradually since motor's torque is in normal state.
- The clack sound may occur when power is ON or OFF on brake • Release the brake before motor drive by supplying power on brake.
- The product life cycle is shorten and the static friction torque reduces due to worn out brake pad.

# Maintain and inspect regularly the following lists.

- Unwinding bolts and connection parts for the unit installation and load connection - Abnormal sound from Ball-bearing of the unit Damage and stress of lead cable of the unit

- Connection error with driver Inconsistency between the axis of motor output and the center, concentric (eccentric, declination) of the load, etc.
- · This unit may be used in the following environments. - Indoors (in the environment condition rated in 'Specifications') - Altitude max. 2,000 m
- Pollution degree 2 - Installation category II

# **Cautions during Installation**

- · Follow instructions in 'Safety Considerations' and 'Cautions during Use'.
- Otherwise, it may cause unexpected accidents. Install the motor in a place that meets the certain conditions specified below. It may cause product damage if it is used out of following conditions.
- Inside of the housing which is installed indoors
- (This unit is designed/manufactured for the purpose of attaching to equipment. Install a ventilation device.)
- The place without contact with water, oil, or other liquid
- The place without contact with strong alkali or acidity
  The place with less electronic noise occurs by welding machine, motor, etc.
- The place where no radioactive substances and magnetic fields exist. It shall be no vacuum status as well.
- · Motor can be installed horizontally and vertically. Refer to 'Shaft Allowable Load along Installation Direction'.
- If a force (30 N) exceeding the specification is applied to the motor cable during installation, it may cause the contact failure and disconnection.
- If the excessive force or frequent cable movement is required, establish safety measures hefore use
- In consideration of heat dissipation and vibration prevention, mount the motor as tight as possible against a metal panel with high thermal conductivity such as iron or aluminum

### **Cautions during Connection with Load**

- Do not disassemble or modify the motor shaft to connect with the load.
- · Tighten the screw not to be unscrewed when connecting with load. Refer to 'Shaft Allowable Load along Installation Direction' and take care of potential shock when connecting with load. • Connect the motor shaft and the load shaft to be parallel.

• If the center with the load is not aligned with the shaft, it may cause unexpected accidents such as severe vibration, shorten life cycle of the shaft bearing and shaft damage. • When attaching coupling or pulley with motor shaft, be aware of damage on motor shaft and shaft bearing

#### ■ Pulley, Belt, Wire ■ Gear Coupling





- - 6 Connect the motor shaft and the line which connects the center of two pulleys to be

Connect the motor shaft to the center of gear teeth to be interlocked

### **Ordering Information**

When connecting the load

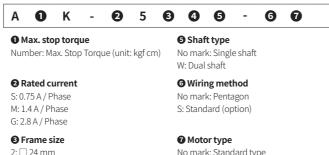
directly to the motor shaft,

use a flexible coupling (ERB

Series).

This is only for reference, the actual product does not support all combinations. For selecting the specified model, follow the Autonics website

perpendicular



No mark: Standard type B: Built-in brake type

Instruction manual

Axial length

Number: Refer to 'Dimensions'

### Product Components

Product

4: 2 42 mm

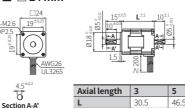
6: 🗌 60 mm

9: 🗌 85 mm

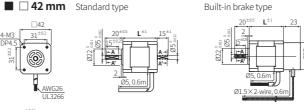
### Dimensions

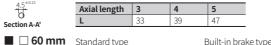
• Unit: mm, For the detailed drawings, follow the Autonics website. · The dotted lines are included in dual shaft type.



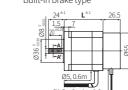


**42 mm** Standard type





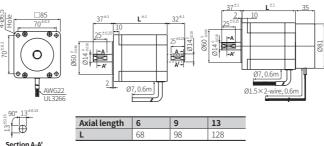








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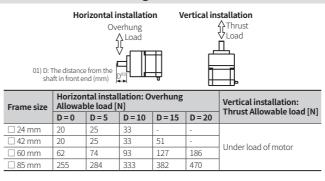


# Installation Method



Frame size	Mounting plate Thickness	Applied bolt
🗌 24 mm	≥3mm	M2.6
🗌 42 mm	$\geq$ 4 mm	M3
🗌 60 mm	≥5mm	M4
🗆 85 mm	≥8mm	M6

### Shaft Allowable Load along Installation Direction



# Specifications

specification	5				
Model	02K-S523		04K-S525		
Max. stop torque	0.18 kgf cm (0.018 N m)		0.28 kgf cm (0.028 N m)		
Rotor inertia moment	4.2×10 <sup>-7</sup> kg · m <sup>2</sup>		$8.2 \times 10^{-7} \text{ kg} \cdot \text{m}^2$		
Rated current	0.75 A / Phase				
Basic step angle	0.72° / 0.36° (Full / Half step)				
Unit weight	≈ 0.08 kg (≈ 0.10 kg)		$\approx 0.12 \text{ kg} (\approx 0.16 \text{ kg})$		
(packaged)	~ 0.08 kg (~ 0.10 kg)		~ 0.12 kg (	NB (~ 0.10 NB)	
Model	A1K-S543	A2K-S544	7-0	A3K-S545	
Max. stop torque	1.3 kgf cm (0.13 N m)	1.8 kgf cm (		2.4 kgf cm (0.24 N m)	
Rotor inertia moment	35×10 <sup>-7</sup> kg · m <sup>2</sup>	54×10 <sup>-7</sup> kg · m <sup>2</sup>		$68 \times 10^{-7} \text{ kg} \cdot \text{m}^2$	
Rated current	0.75 A / Phase				
Basic step angle	0.72° / 0.36° (Full / Half step)				
Unit weight	$\approx 0.25 \text{ kg} (\approx 0.34 \text{ kg})$	≈ 0.30 kg (	≈ 0.39 kg)	$\approx 0.40 \text{ kg} (\approx 0.49 \text{ kg})$	
(packaged) <sup>01)</sup>	$\approx 0.39 \text{ kg} (\approx 0.44 \text{ kg})$	≈ 0.44 kg (*	≈ 0.49 kg)	$\approx 0.54 \text{ kg} (\approx 0.59 \text{ kg})$	
Model	A4K-□564□-□	A8K-□566		A16K-□569□-□	
Max. stop torque	4.2 kgf cm (0.42 N m)	8.3 kgf cm (		16.6 kgf cm (1.66 N m)	
Rotor inertia moment		$280 \times 10^{-7} \text{ kg} \cdot \text{m}^2 \qquad 560 \times 10^{-7} \text{ kg} \cdot \text{m}^2$		560×10 <sup>-7</sup> kg · m <sup>2</sup>	
	S: 0.75 A / Phase				
Rated current	M: 1.4 A / Phase				
	G: 2.8 A / Phase				
Basic step angle	0.72° / 0.36° (Full / Half step)				
Unit weight	$\approx 0.60 \text{ kg} (\approx 0.85 \text{ kg})$	≈ 0.80 kg (*		$\approx$ 1.30 kg ( $\approx$ 1.55 kg)	
(packaged) <sup>01)</sup>	$\approx$ 0.95 kg ( $\approx$ 1.03 kg)	≈ 1.25 kg (:	≈ 1.33 kg)	$\approx$ 1.65 kg ( $\approx$ 1.73 kg)	
Model	A21K-□596□-□	A41K-□59	9□-□	A63K-059130-0	
Max. stop torque	21 kgf cm (2.1 N m)	41 kgf cm (4	1.1 N m)	63 kgf cm (6.3 N m)	
Rotor inertia moment		2,700×10-7		4,000×10 <sup>-7</sup> kg · m <sup>2</sup>	
Rated current	M: 1.4 A / Phase				
	G: 2.8 A / Phase				
Basic step angle	0.72° / 0.36° (Full / Half step)				
Unit weight	≈ 1.70 kg (≈ 2.15 kg)	≈ 2.80 kg (*		≈ 3.80 kg (≈ 4.25 kg)	
(packaged) <sup>01)</sup>	≈ 2.64 kg (≈ 2.74 kg)	$\approx 3.74 \text{ kg}(s)$	≈ 3.84 kg)	$\approx$ 4.74 kg ( $\approx$ 4.84 kg)	
Star	ndard type				

01) Listed in order of Standard type Built-in brake type

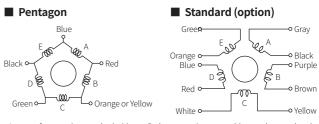
Motor phase	5-phase
Insulation class	B type (130°C)
<b>Insulation resistance</b> Between motor coil and case: $\geq 100 \text{ M}\Omega$ (500 VDC= megger)	
Dielectric strength <sup>01)</sup>	Between motor coil and case: 1,000 VAC $\sim$ 50 / 60 Hz for 1 minute
Temperature rise	$\leq$ 80°C (5-phase excitation for rated current, while stop)
Ambient temp.	-10 to 50°C, storage: -25 to 85°C (no freezing or condensation)
Ambient humi.	35 to 85%RH, storage: 35 to 85%RH (no freezing or condensation)
Protection rating	IP30 (IEC34-5 standard)
Approval	C€EHL
Stop angle error	$\pm$ 3' ( $\pm$ 0.05°) (Full step, no load)
Shaft vibration	0.05 mm T.I.R.
Radial movement <sup>02)</sup>	$\leq$ 0.025 mm T.I.R.
Axial movement <sup>03)</sup>	$\leq$ 0.075 mm T.I.R.
Shaft concentricity	0.075 mm T.I.R.
Shaft perpendicularity	0.075 mm T.I.R.

01) In case of rated current: 0.75 A / Phase, Between motor coil and case: 500 VAC  $\sim$  50 / 60 Hz for 1 minute 02) Amount of radial shaft displacement when applying radial load (5 N) to the end of the shaft.

03) Amount of axial shaft displacement when applying axial load (10 N) to the shaft.

🗆 42 mm	🗆 60 mm	🗆 85 mm	
24 VDC== ±10%			
0.2 A	0.33 A	0.62 A	
$\geq$ 0.18 N m	$\geq$ 0.8 N m	≥ 4.0 N m	
$3 \times 10^{-7} \text{kg} \cdot \text{m}^2$	$29 \times 10^{-7} \text{ kg} \cdot \text{m}^2$	153×10 <sup>-7</sup> kg · m <sup>2</sup>	
tion class B type (130°C)			
Brake is released when power ON, brake is locked when power OFF			
$\leq$ 25 ms	$\leq$ 25 ms	$\leq$ 60 ms	
$\leq$ 15 ms	$\leq$ 20 ms	$\leq$ 15 ms	
	$24 \text{ VDC} = \pm 10\%$ 0.2 A ≥ 0.18 N m $3 \times 10^{-7} \text{ kg} \cdot \text{m}^2$ B type (130°C) Brake is released when ≤ 25 ms	$24 \text{ VDC} = \pm 10\%$ $0.2 \text{ A}$ $0.33 \text{ A}$ $\geq 0.18 \text{ N m}$ $\geq 0.8 \text{ N m}$ $3 \times 10^7 \text{ kg} \cdot \text{m}^2$ $29 \times 10^7 \text{ kg} \cdot \text{m}^2$ B type (130°C)Brake is released when power ON, brake is lockerSrake is released when power ON, brake is locker $\leq 25 \text{ ms}$ $\leq 25 \text{ ms}$	

### **Connection Diagram**



• In case of connecting standard wiring to 5-phase stepping motor driver, make sure that the motor's lead wire connection must be made as table blew.

Pentagon	Standard (option)	
Blue	Gray + Red	
Red	Yellow + Black	
Orange	Orange + White	
Orange Green Black	Brown + Green	
Black	Blue + Purple	
	Blue Red Orange Green	

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